# On Global Smooth Solution of A Semi-Linear System of Wave Equations in $\mathbb{R}^{3}$ 

WU Haigen*

The Graduate School of China Academy of Engineering Physics, PO Box 2101, Beijing 100088, China; and School of Mathematics and Information Science, Henan Polytechnic University, Jiaozuo 454000, China.

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#### Abstract

In this paper we consider the Cauchy problem for a semi-linear system of wave equations with Hamilton structure. We prove the existence of global smooth solution of the system for subcritical case by using conservation of energy and Strichartz's estimate. On the basis of Morawetz-Pohožev identity, we obtain the same result for the critical case.


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## 1 Introduction and main results

This paper is concerned with the Cauchy problem for the non-linear system of wave equations with Hamilton structure in $\mathbb{R}_{+}^{3+1}$

$$
\left\{\begin{array}{l}
u_{t t}-\Delta u=-F_{1}\left(|u|^{2},|v|^{2}\right) u,  \tag{1.1}\\
v_{t t}-\Delta v=-F_{2}\left(|u|^{2},|v|^{2}\right) v, \\
u(0)=\varphi_{1}(x), \quad u_{t}(0)=\psi_{1}(x), \\
v(0)=\varphi_{2}(x), \quad v_{t}(0)=\psi_{2}(x),
\end{array}\right.
$$

where there exists a function $F(\lambda, \mu)$ such that

$$
\begin{equation*}
\frac{\partial F(\lambda, \mu)}{\partial \lambda}=F_{1}(\lambda, \mu), \quad \frac{\partial F(\lambda, \mu)}{\partial \mu}=F_{2}(\lambda, \mu) . \tag{1.2}
\end{equation*}
$$

[^0]The linear case $F_{j}=m_{j}$, where $m_{j} \in \mathbb{R}$ for $j=1,2$, corresponds to the classical KleinGordon system in relativistic particle physics. The constants $m_{j}$ may be interpreted as masses and hence are generally assumed to be nonnegative. In order to model also non-linear phenomenon like quantization, in the 1950s systems of type (1.1) with nonlinearities like $F_{j}=m_{j}+f_{j}$ were proposed as models in relativistic quantum mechanics with local interaction, see, e.g., [1, 2].

Various other models involving non-linearities $F_{j}$ depending also on $u_{t}, v_{t}, \nabla u$ and $\nabla v$ have been studied [3]. To limit our paper to a reasonable length, we restrict our study to non-linearities depending only on $u, v$, i.e., the semi-linear case.

Without loss of generality, and since all important features of our problem already seem to exist in this case, we confine ourselves to real-valued solutions of (1.1). Moreover, we need to impose the following assumptions on the semi-linearities to ensure that (1.1) always has a global solution.
(H1)

$$
\begin{equation*}
\left|F_{1}\right|+\left|\lambda F_{11}\right|+\left|\lambda^{\frac{1}{2}} \mu^{\frac{1}{2}} F_{12}\right|+\left|F_{2}\right|+\left|\lambda^{\frac{1}{2}} \mu^{\frac{1}{2}} F_{21}\right|+\left|\mu F_{22}\right| \leq C\left(1+\lambda^{\frac{k-1}{2}}+\mu^{\frac{k-1}{2}}\right), \tag{1.3}
\end{equation*}
$$

where $F_{i 1}=\partial F_{i} / \partial \lambda, \quad F_{i 2}=\partial F_{i} / \partial \mu, \quad i=1,2$.
(H2)

$$
\begin{equation*}
F(\lambda, \mu) \geq 0, \quad F(0,0)=0, \quad \lambda^{\frac{k+1}{2}}+\mu^{\frac{k+1}{2}} \leq C_{0}\left[1+\frac{1}{2} F(\lambda, \mu)\right] . \tag{1.4}
\end{equation*}
$$

(H3)

$$
\begin{equation*}
\lambda F_{1}(\lambda, \mu)+\mu F_{2}(\lambda, \mu) \geq 2 F(\lambda, \mu), \quad k=5 . \tag{1.5}
\end{equation*}
$$

(H4)

$$
\begin{equation*}
F(\lambda, \mu) \leq C\left(1+\lambda^{\frac{k+1}{2}}+\mu^{\frac{k+1}{2}}\right) . \tag{1.6}
\end{equation*}
$$

It is easy to verify that

$$
F_{1}(\lambda, \mu)=\lambda^{2}+\mu, \quad F_{2}(\lambda, \mu)=\mu^{2}+\lambda, \quad F(\lambda, \mu)=\frac{1}{3} \lambda^{3}+\frac{1}{3} \mu^{3}+\lambda \mu
$$

satisfy (H1)-(H4) with $k=5$.
It is known that the energy associated with (1.1) is defined by

$$
\begin{align*}
E(u, v ; t)= & \frac{1}{2} \int_{\mathbb{R}^{3}}\left[\left|u_{t}(x, t)\right|^{2}+\left|v_{t}(x, t)\right|^{2}+|\nabla u(x, t)|^{2}\right. \\
& \left.+|\nabla v(x, t)|^{2}+F\left(|u(x, t)|^{2},|v(x, t)|^{2}\right)\right] \mathrm{d} x \\
\triangleq & \frac{1}{2} \int_{\mathbb{R}^{3}}\left[\left|u^{\prime}(x, t)\right|^{2}+\left|v^{\prime}(x, t)\right|^{2}+F\left(|u(x, t)|^{2},|v(x, t)|^{2}\right)\right] \mathrm{d} x . \tag{1.7}
\end{align*}
$$

Notice that the above energy involves two kinds of terms: the kinetic term and the potential term involving semi-linearity $F\left(|u|^{2},|v|^{2}\right)$. To make sure that the potential energy
is controlled by the kinetic energy, we need to assume that $k \leq 5$ in view of (H2), (H4) and (1.7). This is because $F\left(|u|^{2},|v|^{2}\right)$ behaves like $|u|^{k+1}+|v|^{k+1}$ and $H^{1}\left(\mathbb{R}^{3}\right) \hookrightarrow L_{\mathrm{loc}}^{q}\left(\mathbb{R}^{3}\right)$ only when $q \leq 6$. The case where $k=5$ is called the critical case since $q=6$ is the critical exponent for the above Sobolev embedding; while the range $1<k<5$ is called the subcritical case.

Our main result is the following theorem.
Theorem 1.1. Let $1<k \leq 5$ and let $F_{1}, F_{2}$ and $F$ satisfy (H1) and (H2). Assume also that (H3) is satisfied when $|u|$ and $|v|$ are larger than a constant if $k=5$. Then (1.1) always has a global smooth $C^{2}$ solution.

We first point out that, in proving Theorem 1.1, we need only consider compactly supported data. More precisely, fix $\chi \in C_{0}^{\infty}\left(\mathbb{R}^{3}\right)$ satisfying $\chi=1$ for $|x| \leq 1$, set

$$
\varphi_{j R}(x)=\chi\left(\frac{x}{R}\right) \varphi_{j}(x), \quad \psi_{j R}(x)=\chi\left(\frac{x}{R}\right) \psi_{j}(x), \quad j=1,2,
$$

and let $\left(u_{R}, v_{R}\right)$ be the solution of (1.1) with data $\left(\varphi_{j R}, \psi_{j R}\right)$. If $t_{0} \in \mathbb{R}_{+}$, denote

$$
\Lambda_{0, t_{0}}=\left\{(x, t): 0 \leq t \leq t_{0},|x| \leq t_{0}-t\right\}
$$

as the backward light cone through $\left(0, t_{0}\right)$. Then $\left(u_{R_{1}}, v_{R_{1}}\right)=\left(u_{R_{2}}, v_{R_{2}}\right)$ in $\Lambda_{0, t_{0}}$ if $R_{1}, R_{2}>t_{0}$, since $\left(u_{R_{1}}, v_{R_{1}}\right)$ and ( $u_{R_{2}}, v_{R_{2}}$ ) both have Cauchy data $\left(\varphi_{j}, \psi_{j}\right)$ in $\Lambda_{0, t_{0}} \cap\left\{(x, 0): x \in \mathbb{R}^{3}\right\}$. $\mathbb{R}_{+}^{3+1}=\bigcup_{t_{0}>0} \Lambda_{0, t_{0}}$ implies that ( $u_{R}, v_{R}$ ) must converge point by point to a solution of (1.1).

The next step is to recall an important Strichartz's estimate [4-6],

$$
\begin{aligned}
& \left\|v^{\prime}(\cdot, t)\right\|_{L^{2}\left(\mathbb{R}^{3}\right)}+\|v\|_{L_{t}^{\frac{2 q}{q-g}} L_{x}^{q}\left(S_{T}\right)} \\
\leq & C_{q}\left\|v^{\prime}(\cdot, 0)\right\|_{L^{2}\left(\mathbb{R}^{3}\right)}+C_{q} \int_{0}^{T}\|F(\cdot, t)\|_{L^{2}\left(\mathbb{R}^{3}\right)} \mathrm{d} t, \quad 6 \leq q<\infty,
\end{aligned}
$$

where $S_{T}=[0, T] \times \mathbb{R}^{3}$, and $v$ is a solution of the problem

$$
\left\{\begin{array}{l}
v_{t t}-\Delta v=F(x, t), \\
v(0)=f(x), \quad v_{t}(0)=g(x) .
\end{array}\right.
$$

Setting $q=12$ and $q=6$ in the above inequality respectively, we obtain

$$
\begin{equation*}
\|v\|_{L_{t}^{4} L_{x}^{12}\left(S_{T}\right)} \leq C\left(\left\|v^{\prime}(\cdot, 0)\right\|_{L^{2}\left(\mathbb{R}^{3}\right)}+\|F\|_{L_{t}^{1} L_{x}^{2}\left(S_{T}\right)}\right), \tag{1.8}
\end{equation*}
$$

as well as

$$
\begin{equation*}
\sup _{0 \leq t \leq T}\|v(\cdot, t)\|_{L^{6}\left(\mathbb{R}^{3}\right)} \leq C\left(\left\|v^{\prime}(\cdot, 0)\right\|_{L^{2}\left(\mathbb{R}^{3}\right)}+\|F\|_{L_{t}^{1} L_{x}^{2}\left(S_{T}\right)}\right) . \tag{1.9}
\end{equation*}
$$

It is well known that, by the local existence theorem, if $(u, v)$ is a $C^{2}$ solution of (1.1) in a half-open strip $\left[0, T_{*}\right) \times \mathbb{R}^{3}$ with compactly supported data, then either $(u, v)$ extends to a $C^{2}$ solution in a larger strip or else ( $u, v$ ) blows up point-wise, that is, $u, v \notin L^{\infty}\left(\left[0, T_{*}\right) \times \mathbb{R}^{3}\right)$. Our next task is to prove that we can replace $L^{\infty}$ by the mixed-norm in the left-hand side of (1.8).

Proposition 1.1. Let $1<k \leq 5$ and $F_{1}, F_{2}$ satisfy (H1). Then, if $\varphi_{j} \in C^{3}, \psi_{j} \in C^{2},(j=1,2)$ are fixed compactly supported functions, then there exists a $T>0$ such that (1.1) has a $C^{2}$ solution (u,v). Moreover, if $T_{*}$ is the supremum of all such times, then either $T_{*}=\infty$, or

$$
u, v \notin L_{t}^{4} L_{x}^{12}\left(\left[0, T_{*}\right) \times \mathbb{R}^{3}\right) .
$$

Proof. The former part of the theorem is trivial. We only need to prove the latter part. Suppose that $0<T_{*}<\infty$ and that $(u, v)$ is a $C^{2}$ solution of $(1.1)$ in $\left[0, T_{*}\right) \times \mathbb{R}^{3}$ satisfying

$$
\begin{equation*}
u, v \in L_{t}^{4} L_{x}^{12}\left(\left[0, T_{*}\right) \times \mathbb{R}^{3}\right) . \tag{1.10}
\end{equation*}
$$

We then show that (1.10) implies

$$
\begin{equation*}
u, v \in L^{\infty}\left(\left[0, T_{*}\right) \times \mathbb{R}^{3}\right) \tag{1.11}
\end{equation*}
$$

Let $0<R<\infty$ be large enough so that the data vanishes for $|x|>R$. Then $u(x, t)=v(x, t)=0$ for $|x|>R+t$. Therefore (H1) implies that, if $0 \leq t_{0}<s<T_{*}$, then for $|\alpha|=0,1$

$$
\begin{align*}
& \left\|\partial_{x}^{\alpha}\left(u F_{1}\right)\right\|_{L_{t}^{1} L_{x}^{2}(I)}+\left\|\partial_{x}^{\alpha}\left(v F_{2}\right)\right\|_{L_{t}^{1} L_{x}^{2}(I)} \\
\leq & C+C\left(\left\||u|^{k-1} \partial_{x}^{\alpha} u\right\|_{L_{t}^{1} L_{x}^{2}(I)}+\left\||u|^{k-1} \partial_{x}^{\alpha} v\right\|_{L_{t}^{1} L_{x}^{2}(I)}\right. \\
& \left.+\left\||v|^{k-1} \partial_{x}^{\alpha} u\right\|_{L_{t}^{1} L_{x}^{2}(I)}+\left\||v|^{k-1} \partial_{x}^{\alpha} v\right\|_{L_{t}^{1} L_{x}^{2}(I)}\right) \tag{1.12}
\end{align*}
$$

where $I=\left[t_{0}, s\right] \times \mathbb{R}^{3}$, the constant $C$ may depend on $R, T_{*}$ and the constant in (H1) but not on $t_{0}$ or $s$.

In fact, if we set $a=u, v$ for $j=1,2$ respectively, then on one hand

$$
\begin{aligned}
\left|a F_{j}\right|=\left|a \| F_{j}\right| & \leq C\left(1+|u|^{k-1}+|v|^{k-1}\right)|a| \\
& =C\left(|a|+|u|^{k-1}|a|+|v|^{k-1}|a|\right)
\end{aligned}
$$

which implies by Hölder inequality that

$$
\begin{aligned}
\left\|a F_{j}\right\|_{L_{t}^{1} L_{x}^{2}(I)} \leq & 2 C T_{*}\left(\frac{4 \pi}{3}\left(R+T_{*}\right)^{3}\right)^{\frac{1}{2}}+2 C\left(\left\||u|^{k-1} u\right\|_{L_{t}^{1} L_{x}^{2}(I)}\right. \\
& \left.+\left\||u|^{k-1} v\right\|_{L_{t}^{1} L_{x}^{2}(I)}+\left\||v|^{k-1} u\right\|_{L_{t}^{1} L_{x}^{2}(I)}+\left\||v|^{k-1} v\right\|_{L_{t}^{1} L_{x}^{2}(I)}\right)
\end{aligned}
$$

On the other hand

$$
\begin{aligned}
\left|\partial_{x}^{\alpha}\left[a F_{j}\right]\right| & =\left|a \frac{\partial F_{j}}{\partial \lambda} \frac{\partial \lambda}{\partial u} \partial_{x}^{\alpha} u+a \frac{\partial F_{j}}{\partial \mu} \frac{\partial \mu}{\partial v} \partial_{x}^{\alpha} v+F_{j} \partial_{x}^{\alpha} a\right| \\
& \leq\left|2 a u F_{j 1} \partial_{x}^{\alpha} u\right|+\left|2 a v F_{j 2} \partial_{x}^{\alpha} v\right|+\left|F_{j} \partial_{x}^{\alpha} a\right|
\end{aligned}
$$

$$
\begin{aligned}
\leq & 3 C\left(1+|u|^{k-1}+|v|^{k-1}\right)\left(\left|\partial_{x}^{\alpha} u\right|+\left|\partial_{x}^{\alpha} v\right|\right) \\
= & 3 C\left(\left|u^{\prime}\right|+\left|v^{\prime}\right|\right)+3 C\left(|u|^{k-1}\left|\partial_{x}^{\alpha} u\right|+|u|^{k-1}\left|\partial_{x}^{\alpha} v\right|\right. \\
& \left.+|v|^{k-1}\left|\partial_{x}^{\alpha} u\right|+|v|^{k-1}\left|\partial_{x}^{\alpha} v\right|\right),
\end{aligned}
$$

for $|\alpha|=1$, which implies that

$$
\begin{aligned}
\left\|\partial_{x}^{\alpha}\left(a F_{j}\right)\right\|_{L_{t}^{1} L_{x}^{2}(I)} \leq & 3 C\left\|1+\frac{1}{2}\right\| u^{\prime}\left\|_{L_{x}^{2}\left(R^{3}\right)}^{2}+\frac{1}{2}\right\| v^{\prime}\left\|_{L_{x}^{2}\left(R^{3}\right)}^{2}\right\|_{L_{t}^{1}\left[t_{0}, s\right]} \\
& +3 C\left(\left\||u|^{k-1} \partial_{x}^{\alpha} u\right\|_{L_{t}^{1} L_{x}^{2}(I)}+\left\||u|^{k-1} \partial_{x}^{\alpha} v\right\|_{L_{t}^{1} L_{x}^{2}(I)}\right. \\
& \left.+\left\||v|^{k-1} \partial_{x}^{\alpha} u\right\|_{L_{t}^{1} L_{x}^{2}(I)}+\left\||v|^{k-1} \partial_{x}^{\alpha} v\right\|_{L_{t}^{1} L_{x}^{2}(I)}\right) \\
\leq & 3 C T_{*}[1+E(u, v ; 0)]+3 C\left(\left\||u|^{k-1} \partial_{x}^{\alpha} u\right\|_{L_{t}^{1} L_{x}^{2}(I)}+\left\||u|^{k-1} \partial_{x}^{\alpha} v\right\|_{L_{t}^{1} L_{x}^{2}(I)}\right. \\
& \left.+\left\||v|^{k-1} \partial_{x}^{\alpha} u\right\|_{L_{t}^{1} L_{x}^{2}(I)}+\left\||v|^{k-1} \partial_{x}^{\alpha} v\right\|_{L_{t}^{1} L_{x}^{2}(I)}\right) .
\end{aligned}
$$

If we choose

$$
C^{\prime}=\max \left(4 C T_{*}\left[\frac{4 \pi}{3}\left(R+T_{*}\right)^{3}\right]^{\frac{1}{2}}, 6 C T_{*}[1+E(u, v ; 0)], 6 C\right)
$$

then $C^{\prime}$ depends on $R, T_{*}$ and the constant in (H1) but not on $t_{0}$ or $s$, still denoted by $C$ in (1.12) for simplicity.

If we use (1.9), with $t$ replaced by $t-t_{0}$, then

$$
\begin{align*}
& \sup _{t_{0} \leq t \leq s|\alpha| \leq 1} \sum_{x}\left\|\partial_{x}^{\alpha} u(\cdot, t)\right\|_{L^{6}\left(\mathbb{R}^{3}\right)}+\sup _{t_{0} \leq t \leq s} \sum_{|\alpha| \leq 1}\left\|\partial_{x}^{\alpha} v(\cdot, t)\right\|_{L^{6}\left(\mathbb{R}^{3}\right)} \\
& \leq C\left(1+\sum_{|\alpha| \leq 1}\left[\left\|\left(\partial_{x}^{\alpha} u\right)^{\prime}\left(\cdot, t_{0}\right)\right\|_{L^{2}\left(\mathbb{R}^{3}\right)}+\left\|\left(\partial_{x}^{\alpha} v\right)^{\prime}\left(\cdot, t_{0}\right)\right\|_{L^{2}\left(\mathbb{R}^{3}\right)}+\left\||u|^{k-1} \partial_{x}^{\alpha} u\right\|_{L_{t}^{1} L_{x}^{2}(I)}\right.\right. \\
& \\
& \quad+\left\||u|^{k-1} \partial_{x}^{\alpha} v\right\|_{L_{t}^{1} L_{x}^{2}(I)}+\left\||v|^{k-1} \partial_{x}^{\alpha} u\right\|_{L_{t}^{1} L_{x}^{2}(I)}+\left\|\left||v|^{k-1} \partial_{x}^{\alpha} v \|_{L_{t}^{1} L_{x}^{2}(I)}\right]\right) \\
& \leq C\left(t_{0}\right)+C \sum_{|\alpha| \leq 1}\left(\left\||u|^{k-1} \partial_{x}^{\alpha} u\right\|_{L_{t}^{1} L_{x}^{L}(I)}+\left\||u|^{k-1} \partial_{x}^{\alpha} v\right\|_{L_{t}^{1} L_{x}^{2}(I)}\right.  \tag{1.13}\\
& \left.\quad+\left\||v|^{k-1} \partial_{x}^{\alpha} u\right\|_{L_{t}^{1} L_{x}^{2}(I)}+\left\||v|^{k-1} \partial_{x}^{\alpha} v\right\|_{L_{t}^{1} L_{x}^{2}(I)}\right)
\end{align*}
$$

where $C\left(t_{0}\right)$ is independent of $s$ and is finite since $(u, v)$ is a $C^{2}$ solution and vanishes for large $|x|$.

Apply Hölder's inequality to the last four terms in (1.13) and consider them in two cases. For simplicity, we take a general term $\left\||a|^{k-1} \partial_{x}^{\alpha} b\right\|_{L_{t}^{1} L_{x}^{2}(I)}$ as an example, where $a, b$ may be $u$ or $v$.

Case 1. $k=5$. In this case,

$$
\begin{aligned}
& C \sum_{|\alpha| \leq 1}\left\||a|^{k-1} \partial_{x}^{\alpha} b\right\|_{L_{t}^{1} L_{x}^{2}(I)}=C \sum_{|\alpha| \leq 1}\left\||a|^{4} \partial_{x}^{\alpha} b\right\|_{L_{t}^{1} L_{x}^{2}(I)} \\
& \leq C \sum_{|\alpha| \leq 1}\left\|\partial_{x}^{\alpha} b\right\|_{L_{t}^{\infty} L_{x}^{L}(I)}\left\||a|^{4}\right\|_{L_{t}^{1} L_{x}^{3}(I)} \leq C \sup _{t_{0} \leq t \leq s|\alpha| \leq 1}\left\|\partial_{x}^{\alpha} b(\cdot, t)\right\|_{L^{6}\left(\mathbb{R}^{3}\right)}\|a\|_{L_{t}^{4} L_{x}^{12}(I)}^{4} .
\end{aligned}
$$

It follows from (1.10) that the last factor must go to zero as $t_{0} \nearrow T_{*}$. By similar arguments to others three terms, we conclude that the last four terms in (1.13) are smaller than half of its left-hand side and so

$$
\sup _{t_{0} \leq t \leq s} \sum_{|\alpha| \leq 1}\left\|\partial_{x}^{\alpha} u(\cdot, t)\right\|_{L^{6}\left(\mathbb{R}^{3}\right)}+\sup _{t_{0} \leq t \leq s|\alpha| \leq 1} \sum_{x}\left\|\partial_{x}^{\alpha} v(\cdot, t)\right\|_{L^{6}\left(\mathbb{R}^{3}\right)} \leq 2 C\left(t_{0}\right) .
$$

Letting $s \nearrow T_{*}$ we conclude that

$$
\begin{equation*}
\sup _{0 \leq t \leq T_{*}|\alpha| \leq 1} \sum_{x}\left\|\partial_{x}^{\alpha} u(\cdot, t)\right\|_{L^{6}\left(\mathbb{R}^{3}\right)}+\sup _{0 \leq t \leq T_{*}|\alpha| \leq 1} \sum_{x}\left\|\partial_{x}^{\alpha} v(\cdot, t)\right\|_{L^{6}\left(\mathbb{R}^{3}\right)}<\infty . \tag{1.11'}
\end{equation*}
$$

This clearly implies (1.11) by using Sobolev's embedding $W^{1,6}\left(\mathbb{R}^{3}\right) \hookrightarrow L^{\infty}\left(\mathbb{R}^{3}\right)$.
Case 2. $1<k<5$. In this case,

$$
\begin{aligned}
& C \sum_{|\alpha| \leq 1}\left\|\left.| | a\right|^{k-1} \partial_{x}^{\alpha} b\right\|_{L_{t}^{1} L_{x}^{2}(I)} \leq C \sup _{t_{0} \leq t \leq s} \sum_{\alpha \mid \leq 1}\left\|\partial_{x}^{\alpha} b(\cdot, t)\right\|_{L^{6}\left(\mathbb{R}^{3}\right)}\|a\|_{L_{t}^{k-1} L_{x}^{3(k-1)}(I)}^{k-1} \\
& \leq C\|1\|_{L_{t}^{x}\left[t_{0}, s\right] L_{x}^{3 x}\left(|x|<T_{*}+R\right)}^{k-1} \sup _{t_{0} \leq t \leq s} \sum_{|\alpha| \leq 1}\left\|\partial_{x}^{\alpha} b(\cdot, t)\right\|_{L^{6}\left(\mathbb{R}^{3}\right)}\|a\|_{L_{t}^{4} L_{x}^{12}(I)}^{k-1} \\
& \leq C\left(R, T_{*}\right) \sup _{t_{0} \leq t \leq s|\alpha| \leq 1} \sum_{x}\left\|\partial_{x}^{\alpha} b(\cdot, t)\right\|_{L^{6}\left(\mathbb{R}^{3}\right)}\|a\|_{L_{t}^{4} L_{x}^{12}(I)^{\prime}}^{k-1}
\end{aligned}
$$

where $1 /(k-1)=1 / 4+1 / \chi$. Since $k>1$, the last part also goes to zero as $t_{0} \nearrow T_{*}$. Using similar argument used in Case 1, we conclude that (1.11) holds in this case. This completes the proof of this proposition.

To prove Theorem 1.1, we only need to consider the following two results for subcritical case and critical case respectively.
Proposition 1.2. Let $1<k<5$ and suppose that $(u, v)$ is a $C^{2}$ solution to (1.1) with a compact Cauchy data supported on $\left\{x \in \mathbb{R}^{3}:|x| \leq R\right\}$. If

$$
\begin{equation*}
E(u, v ; t)=E(u, v ; 0), \quad 0<t<T_{*}, \tag{1.14}
\end{equation*}
$$

then

$$
u, v \in L_{t}^{4} L_{x}^{12}\left(\left[0, T_{*}\right) \times \mathbb{R}^{3}\right) .
$$

Proposition 1.3. Let $k=5$ and suppose that $(u, v)$ is a $C^{2}$ solution to (1.1) with a compact Cauchy data supported on $\left\{x \in \mathbb{R}^{3}:|x| \leq R\right\}$. Fix $x_{0} \in \mathbb{R}^{3}$ and assume that

$$
\begin{equation*}
\int_{\left|x-x_{0}\right| \leq T_{*}-t_{0}} \frac{1}{2}\left(\left|u^{\prime}\left(x, t_{0}\right)\right|^{2}+\left|v^{\prime}\left(x, t_{0}\right)\right|^{2}+F\left(\left|u\left(x, t_{0}\right)\right|^{2},\left|v\left(x, t_{0}\right)\right|^{2}\right)\right) \mathrm{d} x<\varepsilon . \tag{1.15}
\end{equation*}
$$

Then there exists an $\varepsilon_{0}>0$ depending only on $T_{*}, R$ and $E(u, v ; 0)$, such that if $0<\varepsilon<\varepsilon_{0}$ and $0 \leq t_{0}<T_{*}$

$$
\begin{equation*}
u, v \in L_{t}^{4} L_{x}^{12}\left(\Lambda\left(\delta ; t_{0}, T_{*}\right)\right), \tag{1.16}
\end{equation*}
$$

provided that $\delta>0$ and $T_{*}-t_{0}$ are sufficiently small.
To prove Propositions 1.2 and 1.3, we will need to use the following basic lemma.
Lemma 1.1. Suppose that $0 \leq y(s) \in C([a, b))$ satisfies $y(a)=0$ and

$$
y(s) \leq C_{0}+\varepsilon(y(s))^{\sigma},
$$

for some $C>0$ and $\sigma>0$. Then, if $\varepsilon<2^{-\sigma} C_{0}^{1-\sigma}$, then

$$
y(s) \leq 2 C_{0}, \quad s \in[a, b) .
$$

Proof. Consider

$$
h(x)=C_{0}+\varepsilon x^{\sigma}-x .
$$

If $\varepsilon<2^{-\sigma} C_{0}^{1-\sigma}$ and $x_{1}=2 C_{0}$, then

$$
C_{0}+\varepsilon x_{1}^{\sigma}-x_{1}=h\left(x_{1}\right)=h\left(2 C_{0}\right)<C_{0}+2^{-\sigma} C_{0}^{1-\sigma}\left(2 C_{0}\right)^{\sigma}-2 C_{0}=0 .
$$

It follows that if $h(x)=C_{0}+\varepsilon x^{\sigma}-x \geq 0, \forall x \in\left[0, x_{0}\right)$, then $x_{0}<x_{1}=2 C_{0}$. Since $y(s)$ must be smaller than the supremum of such $x_{0}$, the lemma follows.

The paper is organized as follows. In Section 2 the conservation of energy is given to prove the subcritical case of the problem. Section 3 is devoted to the critical case. Morawetz established in her seminal paper [7] Morawetz's identity for Klein-Gordon equations, and for Schrödinger equations similar identity was obtained by Lin and Strauss in [8]. As we know, Morawetz's identity, like other invariants and conservation laws, plays an important role in the scattering theory of nonlinear Klein-Gordon equations (see, e.g., [9-14]) and nonlinear Schrödinger equations (see, e.g., [8, 12, 15]). This work will be concerned with the Morawetz's identity for the wave equation. In Section 3, we use the non-concentration of potential energy to prove the global existence for the critical case of the system. Here a relevant Morawetz's identity will play an important role.

## 2 Proof of Proposition 1.2

To prove the subcritical case, we firstly prove the following conservation of energy.
Proposition 2.1. Suppose that $F_{1}, F_{2}, F$ are as in Theorem 1.1. Suppose also that $0<T_{*}<\infty$ and that $(u, v)$ is a $C^{2}$ solution of (1.1) and that the Cauchy data vanish for $|x|>R$. Then

$$
\begin{equation*}
E(u, v ; t)=E(u, v ; 0), \quad 0<t<T_{*} . \tag{2.1}
\end{equation*}
$$

Moreover, for fixed data as above, there is a constant $C_{R, T_{*}}$ such that

$$
\int_{\mathbb{R}^{3}}\left[\left|u^{\prime}(x, t)\right|^{2}+\left|v^{\prime}(x, t)\right|^{2}+|u(x, t)|^{k+1}+|v(x, t)|^{k+1}\right] \mathrm{d} x \leq C_{R, T_{*} \prime} \quad 0<t<T_{*} .
$$

Proof. It follows from $(u, v)=0$ for $|x|>t+R$ and (H2) that

$$
\begin{aligned}
& \int_{\mathbb{R}^{3}}\left(\left|u^{\prime}\right|^{2}+\left|v^{\prime}\right|^{2}+|u|^{k+1}+|v|^{k+1}\right) \mathrm{d} x \\
\leq & \int_{|x| \leq T_{*}+R}\left(\left|u^{\prime}\right|^{2}+\left|v^{\prime}\right|^{2}+C_{0}+\frac{1}{2} C_{0} F\right) \mathrm{d} x \\
\leq & C\left(\frac{4 \pi}{3}\left(R+T_{*}\right)^{3}+E(u, v ; 0)\right) \triangleq C_{R, T_{*}} .
\end{aligned}
$$

Therefore, (2.1) implies (2.1'). Note that

$$
E(u, v ; 0)=\int_{\mathbb{R}^{3}} \frac{1}{2}\left[\left|\nabla \varphi_{1}\right|^{2}+\left|\nabla \varphi_{2}\right|^{2}+\left|\psi_{1}\right|^{2}+\left|\psi_{2}\right|^{2}+F\left(\left|\varphi_{1}\right|^{2},\left|\varphi_{2}\right|^{2}\right)\right] \mathrm{d} x<\infty,
$$

in view of our assumptions on the data. Multiply $u_{t t}-\Delta u+F_{1} u=0$ and $v_{t t}-\Delta v+F_{2} v=0$ by $u_{t}$ and $v_{t}$ respectively. Summing the resulting equations gives

$$
\begin{align*}
0 & =u_{t}\left(u_{t t}-\Delta u+F_{1} u\right)+v_{t}\left(v_{t t}-\Delta v+F_{2} v\right) \\
& =\frac{1}{2} \frac{\mathrm{~d}}{\mathrm{~d} t}\left|u^{\prime}\right|^{2}+\frac{1}{2} \frac{\mathrm{~d}}{\mathrm{~d} t}\left|v^{\prime}\right|^{2}-\nabla \cdot\left(u_{t} \nabla u\right)-\nabla \cdot\left(v_{t} \nabla v\right)+\frac{1}{2} \frac{\mathrm{~d} F}{\mathrm{~d} t} \\
& \triangleq \operatorname{div}_{x, t} e(u, v), \tag{2.2}
\end{align*}
$$

where, in the present context,

$$
\begin{equation*}
e(u, v)=\left(-u_{t} \nabla u-v_{t} \nabla v, \frac{1}{2}\left|u^{\prime}\right|^{2}+\frac{1}{2}\left|v^{\prime}\right|^{2}+\frac{1}{2} F\right) . \tag{2.3}
\end{equation*}
$$

If we fix $0<t<T_{*}$, then $(u, v)$ is $C^{2}$ and has compact support in $[0, t] \times \mathbb{R}^{3}$. Therefore,
integrating (2.2) leads to

$$
\begin{aligned}
0= & \int_{0}^{t} \int_{\mathbb{R}^{3}} \operatorname{div}_{x, \tau} e(u, v) \mathrm{d} x \mathrm{~d} \tau \\
= & \int_{\mathbb{R}^{3}} \int_{0}^{t} \frac{\partial}{\partial \tau}\left(\frac{1}{2}\left|u^{\prime}\right|^{2}+\frac{1}{2}\left|v^{\prime}\right|^{2}+\frac{1}{2} F\right) \mathrm{d} \tau \mathrm{~d} x \\
= & \frac{1}{2} \int_{\mathbb{R}^{3}}\left[\left|u^{\prime}(x, t)\right|^{2}+\left|v^{\prime}(x, t)\right|^{2}+F\left(|u(x, t)|^{2},|v(x, t)|^{2}\right)\right] \mathrm{d} x \\
& -\frac{1}{2} \int_{\mathbb{R}^{3}}\left[\left|u^{\prime}(x, 0)\right|^{2}+\left|v^{\prime}(x, 0)\right|^{2}+F\left(|u(x, 0)|^{2},|v(x, 0)|^{2}\right)\right] \mathrm{d} x,
\end{aligned}
$$

which gives (2.1). This completes the proof of this proposition.
Proof of Proposition 1.2. It is clear we only need to show that

$$
\begin{equation*}
u, v \in L_{t}^{4} L_{x}^{12}\left(\left[0, T_{*}\right) \times \mathbb{R}^{3}\right), \quad 0<T_{*}<\infty . \tag{2.4}
\end{equation*}
$$

By (1.8) and (1.12), we have for $I=\left[t_{0}, s\right) \times \mathbb{R}^{3}$

$$
\begin{align*}
& \|u\|_{L_{t}^{4} L_{x}^{12}(I)}+\|v\|_{L_{t}^{4} L_{x}^{12}(I)} \\
\leq & C\left(1+\left\|u^{\prime}\left(\cdot, t_{0}\right)\right\|_{L^{2}\left(\mathbb{R}^{3}\right)}+\left\|v^{\prime}\left(\cdot, t_{0}\right)\right\|_{L^{2}\left(\mathbb{R}^{3}\right)}+\left\||u|^{k}\right\|_{L_{t}^{1} L_{x}^{2}(I)}+\left\||v|^{k}\right\|_{L_{t}^{1} L_{x}^{2}(I)}\right) \\
\leq & C\left(2+\frac{1}{2}\left\|u^{\prime}\left(\cdot, t_{0}\right)\right\|_{L^{2}\left(\mathbb{R}^{3}\right)}^{2}+\frac{1}{2}\left\|v^{\prime}\left(\cdot, t_{0}\right)\right\|_{L^{2}\left(\mathbb{R}^{3}\right)}^{2}+\left\||u|^{k}\right\|_{L_{t}^{1} L_{x}^{2}(I)}+\left\||v|^{k}\right\|_{L_{t}^{1} L_{x}^{2}(I)}\right) \\
\leq & C[2+E(u, v ; 0)]+C\left(\left\||u|^{k}\right\|_{L_{t}^{1} L_{x}^{2}(I)}+\left\||v|^{k}\right\|_{L_{t}^{1} L_{x}^{2}(I)}\right), \tag{2.5}
\end{align*}
$$

where we have used the conservation of energy in the last step. Note that

$$
1=\frac{5-k}{4}+\frac{k-1}{4}, \quad \frac{1}{2}=\frac{7-k}{12}+\frac{k-1}{12} .
$$

Applying Hölder's inequality to (2.5), we obtain

$$
\begin{align*}
\left\||u|^{k}\right\|_{L_{t}^{1} L_{x}^{2}(I)} & \leq\|u\|_{L_{t}^{\frac{4}{5-k}} \frac{\frac{12}{L_{x}-k}(I)}{}}\left\|\left.u\right|^{k-1}\right\|_{L_{t}^{\frac{4}{k-1}} L_{x}^{\frac{12}{k-1}}(I)} \\
& =\|u\|_{L_{t}^{\frac{4}{5-k}} \frac{\frac{12}{L_{x}^{7-k}}(I)}{}\|u\|_{L_{t}^{4} L_{x}^{12}(I)}^{k-1}} . \tag{2.6}
\end{align*}
$$

Note that $12 /(7-k)<k+1$ for $1<k<5$. Therefore, since $u(x, t)=0$ when $|x| \geq t+R$, we can use Hölder's inequality again to obtain that

$$
\begin{align*}
\|u\|_{L_{t}^{\frac{4}{5-k}} L_{x}^{\frac{12}{7-k}}(I)} & \leq\left(T_{*}-t_{0}\right)^{\frac{5-k}{4}} \sup _{t_{0} \leq t \leq s}\|u(\cdot, t)\|_{L^{\frac{12}{1-k}}\left(\mathbb{R}^{3}\right)} \\
& \leq C\left(T_{*}-t_{0}\right)^{\frac{5-k}{4}}\left(T_{*}+R\right)^{3\left(\frac{7-k}{12}-\frac{1}{k+1}\right)} \sup _{t_{0} \leq t \leq s}\|u(\cdot, t)\|_{L^{k+1}\left(\mathbb{R}^{3}\right)} \\
& \leq C_{R, T_{*}}^{\prime}\left(T_{*}-t_{0}\right)^{\frac{5-k}{4}}, \tag{2.7}
\end{align*}
$$

where

$$
C_{R, T_{*}}^{\prime}=C\left(T_{*}+R\right)^{3\left(\frac{7-k}{12}-\frac{1}{k+1}\right)} C_{R, T_{*}} .
$$

Similarly, we have

$$
\begin{align*}
& \left\||v|^{k}\right\|_{L_{t}^{1} L_{x}^{2}(I)} \leq\|v\|_{L_{t}^{\frac{4}{5-k}}} \frac{\frac{12}{L_{x}^{-k}}(I)}{}\|v\|_{L_{t}^{4} L_{x}^{12}(I)^{\prime}}^{k-1}  \tag{2.6'}\\
& \|v\|_{L_{t}^{\frac{4}{5-k}} L_{x}^{\frac{12}{7-k}}(I)} \leq C_{R, T_{*}}^{\prime}\left(T_{*}-t_{0}\right)^{\frac{5-k}{4}} . \tag{2.7'}
\end{align*}
$$

Let

$$
\varepsilon\left(t_{0}\right)=C C_{R, T_{*}}^{\prime}\left(T_{*}-t_{0}\right)^{\frac{5-k}{4}}
$$

where $C$ is as in (2.5). Then using (2.5)-(2.7) gives

$$
\begin{align*}
& \|u\|_{L_{t}^{4} L_{x}^{12}(I)}+\|v\|_{L_{t}^{4} L_{x}^{12}(I)} \\
\leq & C[2+E(u, v ; 0)]+\varepsilon\left(t_{0}\right)\left(\|u\|_{L_{t}^{4} L_{x}^{12}(I)}+\|v\|_{L_{t}^{4} L_{x}^{12}(I)}\right)^{k-1} . \tag{2.8}
\end{align*}
$$

Note that $\varepsilon\left(t_{0}\right) \rightarrow 0$ as $t_{0} \nearrow T_{*}$ since we are assuming $k<5$. Therefore, Lemma 1.1 implies that, if $t_{0}$ is sufficiently close to $T_{*}$, then

$$
\begin{equation*}
\|u\|_{L_{t}^{4} L_{x}^{12}(I)}+\|v\|_{L_{t}^{4} L_{x}^{12}(I)} \leq 2 C[2+E(u, v ; 0)] . \tag{2.4'}
\end{equation*}
$$

This clearly gives (2.4), since, in $\left[0, t_{0}\right] \times \mathbb{R}^{3}, u, v$ is bounded and compactly supported.

## 3 Proof of Proposition 1.3

To prove the critical case, one can not turn to conservation of energy anymore, but this time, we have a local version of the energy identity. Denote

$$
\begin{equation*}
\Lambda\left(\delta ; t_{0}, s\right)=\left\{(x, t): t_{0} \leq t \leq s,\left|x-x_{0}\right| \leq \delta+T_{*}-t\right\} \tag{3.1}
\end{equation*}
$$

which is a portion of the backward light cone through $\left(x_{0}, T_{*}+\delta\right)$. Then the energy in the bottom ball

$$
D_{t_{0}}=\left\{(x, t) \in \Lambda\left(\delta ; t_{0}, s\right): t=t_{0}\right\},
$$

equals to the energy in the top ball

$$
D_{s}=\left\{(x, t) \in \Lambda\left(\delta ; t_{0}, s\right): t=s\right\}
$$

plus the energy flux across the rest of the boundary

$$
M_{t_{0}}^{s}=\left\{(x, t) \in \Lambda\left(\delta ; t_{0}, s\right): t_{0} \leq t \leq s,\left|x-x_{0}\right|=\delta+T_{*}-t\right\}
$$

In other words, let

$$
\begin{align*}
& E\left(u, v ; D_{t}\right)=\int_{D_{t}} \frac{1}{2}\left(\left|u^{\prime}\right|^{2}+\left|v^{\prime}\right|^{2}+F\right) \mathrm{d} x, \quad 0 \leq t<T_{* \prime}  \tag{3.2}\\
& \operatorname{Flux}\left(u, v ; M_{t_{0}}^{s}\right)=\int_{M_{t_{0}}^{s}}\langle e(u, v), \vec{v}\rangle, \quad 0 \leq t_{0}<s \leq T_{*}, \tag{3.3}
\end{align*}
$$

where $e(u, v)$ is as in (2.3), $\vec{v}$ is the outward normal through a given point on $M_{t_{0}}^{s}$. Then

$$
\begin{equation*}
E\left(u, v ; D_{t_{0}}\right)=E\left(u, v ; D_{s}\right)+\operatorname{Flux}\left(u, v ; M_{t_{0}}^{s}\right) . \tag{3.4}
\end{equation*}
$$

Firstly, we need to prove that (H2) implies that the energy flux is nonnegative. To verify this, we note that $M_{t_{0}}^{s}$ consists of points of the form $\left(x, \delta+T_{*}-\left|x-x_{0}\right|\right)$ with $\delta+T_{*}-\mid x-$ $x_{0} \mid \in\left[t_{0}, s\right]$. Moreover, since the outward normal is $(-y /|y|, 1) / \sqrt{2}$, where $y=x_{0}-x$, we have

$$
\begin{align*}
\sqrt{2}\langle e(u, v), \vec{v}\rangle & =\left(-u_{t} \nabla u-v_{t} \nabla v\right) \cdot \frac{-y}{|y|}+\frac{1}{2}\left|u^{\prime}\right|^{2}+\frac{1}{2}\left|v^{\prime}\right|^{2}+\frac{1}{2} F \\
& =\frac{1}{2}\left|\frac{y}{|y|} u_{t}+\nabla u\right|^{2}+\frac{1}{2}\left|\frac{y}{|y|} v_{t}+\nabla v\right|^{2}+\frac{1}{2} F \geq 0 . \tag{3.5}
\end{align*}
$$

Since Flux $\geq 0$, we conclude from (3.4) that $t \rightarrow E\left(u, v ; D_{t}\right)$ is a non-increasing function on $\left[0, T_{*}\right)$. It is also bounded, as $E\left(u, v, D_{t}\right) \leq E(u, v ; t)=E(u, v ; 0)<\infty$. Hence, the first two terms in (3.4) must approach a common limit. This in turn gives the important fact that

$$
\operatorname{Flux}\left(u, v ; M_{t_{0}}^{s}\right) \rightarrow 0 \quad \text { as } \quad t \rightarrow T_{*}
$$

Proof of Proposition 1.3. Let $C_{0}$ be the constant in (H2). Then (1.15) implies that

$$
\sup _{t_{0} \leq t<T_{*}} \int_{\left|x-x_{0}\right| \leq \delta+T_{*}-t}\left[|u(x, t)|^{6}+|v(x, t)|^{6}\right] \mathrm{d} x<2 C_{0} \varepsilon
$$

provided that $\delta>0$ and $T_{*}-t_{0}$ are sufficiently small. In fact, for $\delta>0$ small enough, (1.15) implies that

$$
\int_{\left|x-x_{0}\right| \leq \delta+T_{*}-t_{0}} \frac{1}{2}\left[\left|u^{\prime}\left(x, t_{0}\right)\right|^{2}+\left|v^{\prime}\left(x, t_{0}\right)\right|^{2}+F\left(\left|u\left(x, t_{0}\right)\right|^{2},\left|v\left(x, t_{0}\right)\right|^{2}\right)\right]<\frac{3}{2} \varepsilon,
$$

which yields

$$
\sup _{t_{0} \leq t<T_{*}} \int_{\left|x-x_{0}\right| \leq \delta+T_{*}-t} \frac{1}{2}\left[\left|u^{\prime}(x, t)\right|^{2}+\left|v^{\prime}(x, t)\right|^{2}+F\left(|u(x, t)|^{2},|v(x, t)|^{2}\right)\right]<\frac{3}{2} \varepsilon,
$$

where we have used the fact that $E\left(u, v ; D_{t}\right)$ is a non-increasing function of $t$. It is easy to see by (H2) that

$$
\begin{aligned}
& \int_{\left|x-x_{0}\right| \leq \delta+T_{*}-t}\left[|u(x, t)|^{6}+|v(x, t)|^{6}\right] \mathrm{d} x \\
\leq & \frac{4 \pi}{3} C_{0}\left(\delta+T_{*}-t_{0}\right)^{3}+C_{0} \int_{\left|x-x_{0}\right| \leq \delta+T_{*}-t} \frac{1}{2} F \mathrm{~d} x \\
\leq & \frac{4 \pi}{3} C_{0}\left(\delta+T_{*}-t_{0}\right)^{3}+\frac{3}{2} C_{0} \varepsilon .
\end{aligned}
$$

If we choose $\delta$ and $t_{0}$ small enough such that $\frac{4 \pi}{3}\left(\delta+T_{*}-t_{0}\right)^{3}<\frac{1}{2} \varepsilon$, then $\left(1.15^{\prime}\right)$ must hold.
To prove (1.16), we need to use (1.8) where the norm on the left-hand side is only taken over $\Lambda\left(\delta ; t_{0}, s\right)$ and the norm on the right-hand side need only be taken over the same set by Huygen's principle. Thus for $J=\Lambda\left(\delta ; t_{0}, s\right)$,

$$
\begin{align*}
& \|u\|_{L_{t}^{4} L_{x}^{12}(J)}+\|v\|_{L_{t}^{4} L_{x}^{12}(J)} \\
\leq & C\left(\left\|u^{\prime}\left(\cdot, t_{0}\right)\right\|_{L^{2}\left(\mathbb{R}^{3}\right)}+\left\|v^{\prime}\left(\cdot, t_{0}\right)\right\|_{L^{2}\left(\mathbb{R}^{3}\right)}\right)+C\left\|F_{1} u\right\|_{L_{t}^{1} L_{x}^{2}(J)}+C\left\|F_{2} v\right\|_{L_{t}^{1} L_{x}^{2}(J)} \\
\leq & C\left(\frac{1}{2}+\frac{1}{2}\left\|u^{\prime}\left(\cdot, t_{0}\right)\right\|_{L^{2}\left(\mathbb{R}^{3}\right)}^{2}+\frac{1}{2}+\frac{1}{2}\left\|v^{\prime}\left(\cdot, t_{0}\right)\right\|_{L^{2}\left(\mathbb{R}^{3}\right)}^{2}\right)+C\left\|F_{1} u\right\|_{L_{t}^{1} L_{x}^{2}(J)}+C\left\|F_{2} v\right\|_{L_{t}^{1} L_{x}^{2}(J)} \\
\leq & C[1+E(u, v ; 0)]+C\left\|F_{1} u\right\|_{L_{t}^{1} L_{x}^{2}(J)}+C\left\|F_{2} v\right\|_{L_{t}^{1} L_{x}^{2}(J)} \tag{3.6}
\end{align*}
$$

On the other hand, (1.12) and Hölder's inequality imply that

$$
\begin{aligned}
& \left\|F_{1} u\right\|_{L_{t}^{1} L_{x}^{2}(J)}+\left\|F_{2} v\right\|_{L_{t}^{1} L_{x}^{2}(J)} \\
\leq & C_{1}+C_{1}\left(\left\||u|^{4} u\right\|_{L_{t}^{1} L_{x}^{2}(J)}+\left\||u|^{4} v\right\|_{L_{t}^{1} L_{x}^{2}(J)}+\left\||v|^{4} u\right\|_{L_{t}^{1} L_{x}^{2}(J)}+\left\||v|^{4} v\right\|_{L_{t}^{1} L_{x}^{2}(J)}\right) \\
\leq & C_{1}+C_{1}\left(\|u\|_{L_{t}^{\infty} L_{x}^{6}(J)}\|u\|_{L_{t}^{4} L_{x}^{12}(J)}^{4}+\|u\|_{L_{t}^{\infty} L_{x}^{6}(J)}\|v\|_{L_{t}^{4} L_{x}^{12}(J)}^{4}\right. \\
& \left.+\|v\|_{L_{t}^{\infty} L_{x}^{6}(J)}\|u\|_{L_{t}^{4} L_{x}^{12}(J)}^{4}+\|v\|_{L_{t}^{\infty} L_{x}^{6}(J)}\|v\|_{L_{t}^{4} L_{x}^{12}(J)}^{4}\right)
\end{aligned}
$$

By $\left(1.15^{\prime}\right)$, the $L_{t}^{\infty} L_{x}^{6}(J)$ norm is $\leq\left(2 C_{0} \varepsilon\right)^{\frac{1}{6}}$. Therefore, if we let $C_{2}=C_{1} C$, then

$$
\begin{aligned}
& \|u\|_{L_{t}^{4} L_{x}^{12}(J)}+\|v\|_{L_{t}^{4} L_{x}^{12}(J)} \\
\leq & \left(C[1+E(u, v ; 0)]+C_{2}\right)+2 C_{2}\left(2 C_{0} \varepsilon\right)^{\frac{1}{6}}\left(\|u\|_{L_{t}^{4} L_{x}^{12}(J)}+\|v\|_{L_{t}^{4} L_{x}^{12}(J)}\right) .
\end{aligned}
$$

Since the constants are independent of $s$, an application of Lemma 1.1 gives that

$$
\|u\|_{L_{t}^{4} L_{x}^{12}(J)}+\|v\|_{L_{t}^{4} L_{x}^{12}(J)} \leq 2\left(C[1+E(u, v ; 0)]+C_{2}\right)
$$

provided that

$$
2 C_{2}\left(2 C_{0} \varepsilon\right)^{\frac{1}{6}}<2^{-4}\left(C[1+E(u, v ; 0)]+C_{2}\right)^{-3} .
$$

Since $\varepsilon$ depends only on $T_{*}, R$ and $E(u, v ; 0)$, the proof is complete.
Now we still need to show that the condition of Proposition 1.3 is reasonable, i.e., the energy cannot concentrate at any fixed point $\left(x_{0}, T_{*}\right)$. To this end, it suffices to show that

$$
\begin{equation*}
\lim _{t>T_{*}} \frac{1}{2} \int_{\left|x-x_{0}\right|<T_{*}-t}\left(\left|u^{\prime}\right|^{2}+\left|v^{\prime}\right|^{2}+F\right) \mathrm{d} x=0 . \tag{3.7}
\end{equation*}
$$

Since the energy consists of two kinds of energy-the kinetic energy and the potential energy from $F$, to prove (3.7), we may consider them respectively. For the potential energy, we shall need a so-called Morawetz-Pohožaev identity.
A Morawetz-Pohožaev identity. Consider Lagrangian associated with (1.1):

$$
L(u, v)=\frac{1}{2}\left(\left|u_{t}\right|^{2}+\left|v_{t}\right|^{2}-|\nabla u|^{2}-|\nabla v|^{2}-F\right) .
$$

Therefore, we have

$$
\begin{aligned}
& \left.\frac{\mathrm{d}}{\mathrm{~d} \varepsilon} \int_{\left[-T_{*}, 0\right) \times \mathbb{R}^{3}} L(u+\varepsilon \psi, v+\varepsilon \psi) \mathrm{d} t \mathrm{~d} x\right|_{\varepsilon=0} \\
= & \frac{1}{2} \int_{\left[-T_{*}, 0\right) \times \mathbb{R}^{3}} \frac{\mathrm{~d}}{\mathrm{~d} \varepsilon}\left(\left|(u+\varepsilon \psi)_{t}\right|^{2}+\left|(v+\varepsilon \psi)_{t}\right|^{2}-\sum_{j=1}^{3}\left|(u+\varepsilon \psi)_{j}\right|^{2}-\sum_{j=1}^{3}\left|(v+\varepsilon \psi)_{j}\right|^{2}\right. \\
& \left.-F\left(|u+\varepsilon \psi|^{2},|v+\varepsilon \psi|^{2}\right)\right)\left.\mathrm{d} t \mathrm{~d} x\right|_{\varepsilon=0} \\
= & \int_{\left[-T_{*}, 0\right) \times \mathbb{R}^{3}}\left((u+\varepsilon \psi)_{t} \psi_{t}+(v+\varepsilon \psi)_{t} \psi_{t}-\sum_{j=1}^{3}(u+\varepsilon \psi)_{j} \psi_{j}-\sum_{j=1}^{3}(v+\varepsilon \psi)_{j} \psi_{j}\right. \\
& \left.-\frac{1}{2} \frac{\partial F}{\partial \lambda} \frac{\partial \lambda}{\partial(u+\varepsilon \psi)} \frac{\partial(u+\varepsilon \psi)}{\partial \varepsilon}-\frac{1}{2} \frac{\partial F}{\partial \mu} \frac{\partial \mu}{\partial(v+\varepsilon \psi)} \frac{\partial(v+\varepsilon \psi)}{\partial \varepsilon}\right)\left.\mathrm{d} t \mathrm{~d} x\right|_{\varepsilon=0} \\
= & \int_{\left[-T_{*}, 0\right) \times \mathbb{R}^{3}}\left(u_{t} \psi_{t}+v_{t} \psi_{t}-\sum_{j=1}^{3} u_{j} \psi_{j}-\sum_{j=1}^{3} v_{j} \psi_{j}-F_{1} u \psi-F_{2} v \psi\right) \mathrm{d} t \mathrm{~d} x \\
= & -\int_{\left[-T_{*}, 0\right) \times \mathbb{R}^{3}}\left[\left(u_{t t}-\Delta u+F_{1} u\right) \psi+\left(v_{t t}-\Delta v+F_{2} v\right) \psi\right] \mathrm{d} t \mathrm{~d} x=0,
\end{aligned}
$$

whenever $\psi \in C_{0}^{\infty}\left(\left[-T_{*}, 0\right) \times \mathbb{R}^{3}\right)$. Thus, $(u, v)$ must satisfy the Euler-Langrange equations associated with (1.1)

$$
\begin{aligned}
& \frac{\partial L(u, v)}{\partial u}-\sum_{j=0}^{3} \partial_{j}\left(\frac{\partial L(u, v)}{\partial u_{j}}\right)=0, \\
& \frac{\partial L(u, v)}{\partial v}-\sum_{j=0}^{3} \partial_{j}\left(\frac{\partial L(u, v)}{\partial v_{j}}\right)=0 .
\end{aligned}
$$

If $u_{r}, v_{r}$ are one-parameter $C^{1}$ deformations of $u, v$ respectively, then

$$
\begin{aligned}
\partial_{r} L\left(u_{r}, v_{r}\right)= & \frac{\partial L\left(u_{r}, v_{r}\right)}{\partial u_{r}} \partial_{r} u_{r}+\frac{\partial L\left(u_{r}, v_{r}\right)}{\partial v_{r}} \partial_{r} v_{r} \\
& +\sum_{j=0}^{3} \frac{\partial L\left(u_{r}, v_{r}\right)}{\partial u_{r j}} \partial_{j} \partial_{r} u_{r}+\sum_{j=0}^{3} \frac{\partial L\left(u_{r}, v_{r}\right)}{\partial v_{r j}} \partial_{j} \partial_{r} v_{r} .
\end{aligned}
$$

If we assume that $u_{r_{0}}=u$ and $v_{r_{0}}=v$, then

$$
\begin{equation*}
\left.\partial_{r} L\left(u_{r}, v_{r}\right)\right|_{r=r_{0}}=\sum_{j=0}^{3} \partial_{j}\left(\frac{\partial L(u, v)}{\partial u_{j}} \partial_{r} u+\frac{\partial L(u, v)}{\partial v_{j}} \partial_{r} v\right) \tag{3.8}
\end{equation*}
$$

For the Morawetz identity we need arise from the deformations

$$
u_{r}(x, t)=r u(r x, r t), \quad v_{r}(x, t)=r v(r x, r t)
$$

with $r_{0}=1$. In this case,

$$
\begin{aligned}
& \left.\partial_{r} u_{r}\right|_{r=1}=u(r x, r t)+\left.\sum_{j=0}^{3} r u_{j}(r x, r t) x_{j}\right|_{r=1}=u(x, t)+\sum_{j=0}^{3} u_{j}(x, t) x_{j}, \\
& \left.\partial_{r} v_{r}\right|_{r=1}=v(x, t)+\sum_{j=0}^{3} v_{j}(x, t) x_{j} .
\end{aligned}
$$

Note also that

$$
\begin{aligned}
\partial_{j} u_{r} & =\partial_{j}[r u(r x, r t)] \\
\partial_{j} v_{r} & =\partial_{j}[r v(r x, r t)]
\end{aligned}=r \partial_{j} u(r x, r t) r=r^{2} \partial_{j} u(r x, r t) r=r^{2} \partial_{j} v(r x, r t) ., ~ \$
$$

Consequently,

$$
L\left(u_{r}, v_{r}\right)=r^{4}[L(u, v)](r x, r t)+\frac{1}{2} r^{4} F\left(|u(r x, r t)|^{2},|v(r x, r t)|^{2}\right)-\frac{1}{2} F\left(\left|u_{r}\right|^{2},\left|v_{r}\right|^{2}\right),
$$

and hence

$$
\begin{aligned}
& \left.\partial_{r} L\left(u_{r}, v_{r}\right)\right|_{r=1} \\
= & \left\{r^{4} \partial_{r}([L(u, v)](r x, r t))+4 r^{3}[L(u, v)](r x, r t)+2 r^{3} F\left(|u(r x, r t)|^{2},|v(r x, r t)|^{2}\right)\right. \\
& \left.+\frac{1}{2} r^{4} \partial_{r}\left[F\left(|u(r x, r t)|^{2},|v(r x, r t)|^{2}\right)\right]-\frac{1}{2} \partial_{r}\left[F\left(\left|u_{r}\right|^{2},\left|v_{r}\right|^{2}\right)\right]\right\}\left.\right|_{r=1} \\
\triangleq & I+I I+I I I+I V+V .
\end{aligned}
$$

It can be verified that

$$
\begin{aligned}
I V & =\left.\frac{1}{2} r^{4}\left(\frac{\partial F}{\partial \lambda} \frac{\partial \lambda}{\partial u(r x, r t)} \frac{\partial u(r x, r t)}{\partial r}+\frac{\partial F}{\partial \mu} \frac{\partial \mu}{\partial v(r x, r t)} \frac{\partial v(r x, r t)}{\partial r}\right)\right|_{r=1} \\
& =F_{1} u \frac{\partial u}{\partial r}+F_{2} v \frac{\partial v}{\partial r}
\end{aligned}
$$

and

$$
\begin{aligned}
V & =-\left.\frac{1}{2}\left(\frac{\partial F}{\partial \lambda} \frac{\partial \lambda}{\partial u_{r}} \frac{\partial u_{r}}{\partial r}+\frac{\partial F}{\partial \mu} \frac{\partial \mu}{\partial v_{r}} \frac{\partial v_{r}}{\partial r}\right)\right|_{r=1} \\
& =-\left.\left\{F_{1} u_{r}\left[u(r x, r t)+r \frac{\partial u(r x, r t)}{\partial r}\right]+F_{2} v_{r}\left[v(r x, r t)+r \frac{\partial v(r x, r t)}{\partial r}\right]\right\}\right|_{r=1} \\
& =-F_{1}|u|^{2}-F_{1} u \frac{\partial u}{\partial r}-F_{2}|v|^{2}-F_{2} v \frac{\partial v}{\partial r}
\end{aligned}
$$

Consequently,

$$
I+I I+I I I+I V+V=\sum_{j=0}^{3} x_{j} \partial_{j} L(u, v)+4 L(u, v)+2 F-F_{1}|u|^{2}-F_{2}|v|^{2} .
$$

Combing this with (3.8) leads to

$$
\begin{aligned}
& \sum_{j=0}^{3} \partial_{j}\left\{\frac{\partial L(u, v)}{\partial u_{j}}\left[u+\sum_{k=0}^{3} x_{k} u_{k}\right]+\frac{\partial L(u, v)}{\partial v_{j}}\left[v+\sum_{k=0}^{3} x_{k} v_{k}\right]-x_{j} L(u, v)\right\} \\
= & 2 F-F_{1}|u|^{2}-F_{2}|v|^{2} .
\end{aligned}
$$

Using the definition of our Lagrangian, we can rewrite the above equation as

$$
\begin{equation*}
\operatorname{div}_{x, t}\left(-t P, t Q+u_{t} u+v_{t} v\right)=2 F-F_{1}|u|^{2}-F_{2}|v|^{2} \tag{3.9}
\end{equation*}
$$

where

$$
\begin{aligned}
Q= & \frac{1}{2}\left|u^{\prime}\right|^{2}+\frac{1}{2}\left|v^{\prime}\right|^{2}+\frac{1}{2} F+u_{t} \frac{x \cdot \nabla u}{t}+v_{t} \frac{x \cdot \nabla v}{t}, \\
P= & \left(\frac{1}{2}\left|u_{t}\right|^{2}+\frac{1}{2}\left|v_{t}\right|^{2}-\frac{1}{2}|\nabla u|^{2}-\frac{1}{2}|\nabla v|^{2}-\frac{1}{2} F\right) \frac{x}{t}+\left(\frac{u}{t}+u_{t}+\frac{x \cdot \nabla u}{t}\right) \nabla u \\
& +\left(\frac{v}{t}+v_{t}+\frac{x \cdot \nabla v}{t}\right) \nabla v .
\end{aligned}
$$

In fact, note that

$$
\begin{aligned}
& \frac{\partial L(u, v)}{\partial u_{t}}\left[u+\sum_{k=0}^{3} x_{k} u_{k}\right]+\frac{\partial L(u, v)}{\partial v_{t}}\left[v+\sum_{k=0}^{3} x_{k} v_{k}\right]-t L(u, v) \\
= & u_{t}\left(u+t u_{t}+x \cdot \nabla u\right)+v_{t}\left(v+t v_{t}+x \cdot \nabla v\right) \\
& \quad-\frac{t}{2}\left(\left|u_{t}\right|^{2}+\left|v_{t}\right|^{2}-|\nabla u|^{2}-|\nabla v|^{2}-F\right) \\
= & u_{t} u+t\left|u_{t}\right|^{2}+u_{t} x \cdot \nabla u+v_{t} v+t\left|v_{t}\right|^{2}+v_{t} x \cdot \nabla v \\
& \quad-\frac{t}{2}\left(\left|u_{t}\right|^{2}+\left|v_{t}\right|^{2}-|\nabla u|^{2}-|\nabla v|^{2}-F\right) \\
= & u_{t} u+v_{t} v+\frac{t}{2}\left|u^{\prime}\right|^{2}+\frac{t}{2}\left|v^{\prime}\right|^{2}+\frac{t}{2} F+u_{t} x \cdot \nabla u+v_{t} x \cdot \nabla v \\
\triangleq & I
\end{aligned}
$$

which implies that

$$
\frac{\left(I-u_{t} u-v_{t} v\right)}{t}=\frac{1}{2}\left|u^{\prime}\right|^{2}+\frac{1}{2}\left|v^{\prime}\right|^{2}+\frac{1}{2} F+u_{t} \frac{x \cdot \nabla u}{t}+v_{t} \frac{x \cdot \nabla v}{t}=Q .
$$

On the other hand,

$$
\begin{aligned}
& \frac{\partial L(u, v)}{\partial u_{j}}\left[u+\sum_{k=0}^{3} x_{k} u_{k}\right]+\frac{\partial L(u, v)}{\partial v_{j}}\left[v+\sum_{k=0}^{3} x_{k} v_{k}\right]-x_{j} L(u, v) \\
= & -u_{j}\left(u+t u_{t}+x \cdot \nabla u\right)-v_{j}\left(v+t v_{t}+x \cdot \nabla v\right) \\
& -\frac{x_{j}}{2}\left(\left|u_{t}\right|^{2}+\left|v_{t}\right|^{2}-|\nabla u|^{2}-|\nabla v|^{2}-F\right) \\
\triangleq & I I_{j},
\end{aligned}
$$

which yields that

$$
\begin{aligned}
P_{j}=\frac{I I_{j}}{-t}= & u_{j}\left(\frac{u}{t}+u_{t}+\frac{x \cdot \nabla u}{t}\right)+v_{j}\left(\frac{v}{t}+v_{t}+\frac{x \cdot \nabla v}{t}\right) \\
& +\frac{1}{2}\left(\left|u_{t}\right|^{2}+\left|v_{t}\right|^{2}-|\nabla u|^{2}-|\nabla v|^{2}-F\right) \frac{x_{j}}{t} .
\end{aligned}
$$

Consequently,

$$
\begin{aligned}
P= & \left(\frac{1}{2}\left|u_{t}\right|^{2}+\frac{1}{2}\left|v_{t}\right|^{2}-\frac{1}{2}|\nabla u|^{2}-\frac{1}{2}|\nabla v|^{2}-\frac{1}{2} F\right) \frac{x}{t}+\left(\frac{u}{t}+u_{t}+\frac{x \cdot \nabla u}{t}\right) \nabla u \\
& +\left(\frac{v}{t}+v_{t}+\frac{x \cdot \nabla v}{t}\right) \nabla v .
\end{aligned}
$$

Now we shall use the so-called Morawetz-Pohožaev identity we just obtained above to prove the non-concentration of the energy from $F$. We shift $\left(x_{0}, T_{*}\right)$ to the origin again for simplicity.

Proposition 3.1. Let $k=5$ and let $(u, v)$ be as in Proposition 1.3. Then

$$
\lim _{t / T_{*}} \frac{1}{2} \int_{|x|<t} F \mathrm{~d} x=0
$$

Proof. If $T_{*}<T<S \leq 0$, we set

$$
\begin{aligned}
& D_{T}=\{(x, T):|x| \leq-T\} \\
& \Lambda(T, S)=\{(x, t): T \leq t \leq S, \quad|x| \leq-t\} \\
& M_{T}^{S}=\{(x, t): T \leq t \leq S, \quad|x|=-t\}
\end{aligned}
$$

If we integrate (3.9) and apply the divergence theorem, we obtain

$$
\begin{aligned}
& \int_{D_{S}}\left(S Q+u_{t} u+v_{t} v\right) \mathrm{d} x+J+J J \\
= & \iint_{\Lambda(T, S)}\left(2 F-F_{1}|u|^{2}-F_{2}|v|^{2}\right) \mathrm{d} x \mathrm{~d} t
\end{aligned}
$$

where

$$
\begin{aligned}
& J=-\int_{D_{T}}\left(T Q+u_{t} u+v_{t} v\right) \mathrm{d} x \\
& J J=\frac{1}{\sqrt{2}} \int_{M_{T}^{0}}\left(t Q+u_{t} u+v_{t} v+x \cdot P\right) \mathrm{d} \sigma
\end{aligned}
$$

Using Proposition 2.1 and Höder's inequality one finds that the first term goes to zero as $S \nearrow 0$. Thus

$$
J+J J=\iint_{\Lambda(T, 0)}\left(2 F-F_{1}|u|^{2}-F_{2}|v|^{2}\right) \mathrm{d} x \mathrm{~d} t
$$

Using the assumption (H3), i.e., $F_{1}|u|^{2}+F_{2}|v|^{2} \geq 2 F$ when $|u|,|v|$ are larger than a fixed constant, we conclude that

$$
\begin{equation*}
J+J J \leq C T^{4} . \tag{3.10}
\end{equation*}
$$

In fact, $E(u, v ; t)=E(u, v ; 0)<\infty$, implies that

$$
\int_{\mathbb{R}^{3}} F \mathrm{~d} x<\infty .
$$

On the other hand, the fact $F \geq 0$ and $F$ is continuous implies that $F$ is bounded by some constant $M$, while (H1) leads to

$$
\begin{aligned}
& \left.\left|F_{1}\right| u\right|^{2}+F_{2}|v|^{2} \mid \\
\leq & C\left(1+|u|^{k-1}+|v|^{k-1}\right)\left(|u|^{2}+|v|^{2}\right) \leq C\left(1+|u|^{k+1}+|v|^{k+1}\right),
\end{aligned}
$$

where we have used the facts that

$$
|u|^{k-1}|v|^{2},|v|^{k-1}|u|^{2} \leq(\max (|u|,|v|))^{k+1} \leq|u|^{k+1}+|v|^{k+1}
$$

and $|\cdot|^{2} \leq C\left(1+|\cdot|^{k+1}\right)$ for $k>1$. Therefore,

$$
\begin{aligned}
J+J J & =\iint_{\Lambda(T, 0)}\left(2 F-F_{1}|u|^{2}-F_{2}|v|^{2}\right) \mathrm{d} x \mathrm{~d} t \\
& \leq \iint_{\Lambda(T, 0)}\left(2 F+C\left[1+|u|^{k+1}+|v|^{k+1}\right]\right) \mathrm{d} x \mathrm{~d} t \\
& \leq \iint_{\Lambda(T, 0)}\left(2 F+C+C C_{0}\left[1+\frac{F}{2}\right]\right) \mathrm{d} x \mathrm{~d} t \\
& =\iint_{\Lambda(T, 0)}\left[\left(2+\frac{C C_{0}}{2}\right) F+\left(C+C C_{0}\right)\right] \mathrm{d} x \mathrm{~d} t \\
& \leq \iint_{\Lambda(T, 0)}\left[\left(2+\frac{C C_{0}}{2}\right) M+\left(C+C C_{0}\right)\right] \mathrm{d} x \mathrm{~d} t \\
& \leq\left[\left(2+\frac{C C_{0}}{2}\right) M+\left(C+C C_{0}\right)\right] \int_{0}^{|T|} \frac{4 \pi}{3}|t|^{3} \mathrm{~d} t \leq C T^{4}
\end{aligned}
$$

To exploit (3.10), we need to obtain a lower bound for $J$ and $J J$. Note that $t=-|x|$ on $M_{T}^{0}$. We rewrite JJ as

$$
\begin{aligned}
J J= & \frac{1}{\sqrt{2}} \int_{M_{T}^{0}}\left(t Q+u_{t} u+v_{t} v+x \cdot P\right) \mathrm{d} \sigma \\
= & \frac{1}{\sqrt{2}} \int_{M_{T}^{0}}\left(-\frac{|x|}{2}\left|u^{\prime}\right|^{2}-\frac{|x|}{2}\left|v^{\prime}\right|^{2}-\frac{|x|}{2} F+u_{t} x \cdot \nabla u+v_{t} x \cdot \nabla v+u_{t} u+v_{t} v\right. \\
& -\frac{u}{|x|} x \cdot \nabla u+u_{t} x \cdot \nabla u-\frac{1}{|x|}(x \cdot \nabla u)^{2}-\frac{v}{|x|} x \cdot \nabla v+v_{t} x \cdot \nabla v-\frac{1}{|x|}(x \cdot \nabla v)^{2} \\
& \left.+\frac{|x|}{2}|\nabla u|^{2}+\frac{|x|}{2}|\nabla v|^{2}-\frac{|x|}{2}\left|u_{t}\right|^{2}-\frac{|x|}{2}\left|v_{t}\right|^{2}+\frac{|x|}{2} F\right) \mathrm{d} \sigma \\
= & \frac{1}{\sqrt{2}} \int_{M_{T}^{0}}\left(-\left|x \| u_{t}\right|^{2}-|x|\left|v_{t}\right|^{2}+2 u_{t} x \cdot \nabla u+2 v_{t} x \cdot \nabla v+u_{t} u+v_{t} v\right. \\
= & \left.-\frac{1}{|x|}(x \cdot \nabla u)^{2}-\frac{1}{|x|}(x \cdot \nabla v)^{2}-\frac{u}{|x|} x \cdot \nabla u-\frac{v}{|x|} x \cdot \nabla v\right) \mathrm{d} \sigma \\
& +|x|\left(\frac{1}{\sqrt{2}} \int_{M_{T}^{0}}\left(|x \cdot \nabla v|\left(\frac{x \cdot \nabla u}{|x|}-v_{t}\right)^{2}+v\left(\frac{x \cdot \nabla v}{|x|}-v_{t}\right)\right) \mathrm{d} \sigma .\right.
\end{aligned}
$$

If we parameterize $M_{T}^{0}$ by

$$
y \longrightarrow(y,-|y|), \quad|y| \leq-T
$$

then $\mathrm{d} \sigma=\sqrt{2} \mathrm{~d} y$. If we set $\bar{u}(y)=u(y,-|y|)$ and $\bar{v}(y)=v(y,-|y|)$, then

$$
\begin{aligned}
& y \cdot \frac{\nabla \bar{u}}{|y|}=\frac{x \cdot \nabla u}{|x|}-u_{t}, \\
& y \cdot \frac{\nabla \bar{v}}{|y|}=\frac{x \cdot \nabla v}{|x|}-v_{t},
\end{aligned}
$$

where $\nabla \bar{u}=\sum_{j=0}^{3} \partial_{j} \bar{u}$ and $\nabla u=\sum_{j=1}^{3} \partial_{j} u$. Therefore

$$
\begin{aligned}
J J= & -\int_{|y| \leq|T|}\left(\frac{|y \cdot \nabla \bar{u}|^{2}}{|y|}+\bar{u} \frac{y \cdot \nabla \bar{u}}{|y|}+\frac{|y \cdot \nabla \bar{v}|^{2}}{|y|}+\bar{v} \frac{y \cdot \nabla \bar{v}}{|y|}\right) \mathrm{d} y \\
= & -\int_{|y| \leq|T|} \frac{1}{|y|}\left(|y \cdot \nabla \bar{u}+\bar{u}|^{2}+|y \cdot \nabla \bar{v}+\bar{v}|^{2}\right) \mathrm{d} y \\
& +\int_{|y| \leq|T|} \frac{1}{|y|}\left(|\bar{u}|^{2}+\bar{u} y \cdot \nabla \bar{u}+|\bar{v}|^{2}+\bar{v} y \cdot \nabla \bar{v}\right) \mathrm{d} y .
\end{aligned}
$$

To evaluate the second term, note that, if we use polar coordinates $y=r \omega$, then

$$
\bar{u} y \cdot \nabla \bar{u} /|y|=\bar{u} \partial_{r} \bar{u}=\frac{1}{2} \partial_{r}\left(\bar{u}^{2}\right) .
$$

Hence, integration by parts gives

$$
\begin{aligned}
\int_{|y| \leq|T|} \bar{u} \frac{y \cdot \nabla \bar{u}}{|y|} \mathrm{d} y & =\frac{1}{2} \int_{S^{2}} \int_{0}^{|T|} \partial_{r}\left[\bar{u}^{2}(r \omega)\right] r^{2} \mathrm{~d} r \mathrm{~d} \sigma(\omega) \\
& =\frac{1}{2} \int_{S^{2}} \bar{u}^{2}(|T| \omega)|T|^{2} \mathrm{~d} \sigma(\omega)-\int_{S^{2}} \int_{0}^{|T|} \bar{u}^{2}(r \omega) r \mathrm{~d} r \mathrm{~d} \sigma(\omega) \\
& =\frac{1}{2} \int_{\partial D_{T}} u^{2} \mathrm{~d} \sigma-\int_{|y| \leq|T|} \frac{\bar{u}^{2}}{|y|} \mathrm{d} y,
\end{aligned}
$$

and

$$
\int_{|y| \leq|T|} \frac{\bar{v}}{} \frac{y \cdot \nabla \bar{v}}{|y|} \mathrm{d} y=\frac{1}{2} \int_{\partial D_{T}} v^{2} \mathrm{~d} \sigma-\int_{|y| \leq|T|} \frac{\bar{v}^{2}}{|y|} \mathrm{d} y .
$$

Combing these with the earlier formula and switching back to the original coordinates gives

$$
\begin{align*}
J J= & \frac{1}{\sqrt{2}} \int_{M_{T}^{0}}\left(t\left|\frac{x}{|x|} \cdot \nabla u-u_{t}+\frac{u}{|x|}\right|^{2}+t\left|\frac{x}{|x|} \cdot \nabla v-v_{t}+\frac{v}{|x|}\right|^{2}\right) \mathrm{d} \sigma \\
& +\frac{1}{2} \int_{\partial D_{T}}\left(u^{2}+v^{2}\right) \mathrm{d} \sigma . \tag{3.11}
\end{align*}
$$

When it comes to $J$, we first notice that

$$
\begin{aligned}
T Q+u_{t} u+v_{t} v & =T\left(\frac{1}{2}\left|u^{\prime}\right|^{2}+\frac{1}{2}\left|v^{\prime}\right|^{2}+\frac{1}{2} F+\frac{u_{t}}{T} x \cdot \nabla u+\frac{v_{t}}{T} x \cdot \nabla v\right)+u_{t} u+v_{t} v \\
& =T\left(\frac{1}{2}\left|u^{\prime}\right|^{2}+\frac{1}{2}\left|v^{\prime}\right|^{2}+\frac{1}{2} F\right)+u_{t}(u+x \cdot \nabla u)+v_{t}(v+x \cdot \nabla v)
\end{aligned}
$$

while

$$
\begin{aligned}
\left|u_{t}(u+x \cdot \nabla u)\right| & =\left|u_{t}\left(\frac{x \cdot x}{|x|^{2}} u+x \cdot \nabla u\right)\right|=\left|u_{t} x \cdot\left(\frac{x}{|x|} u+\nabla u\right)\right| \\
& =\left|x \cdot u_{t}\left(\frac{x}{|x|} u+\nabla u\right)\right| \leq-T\left(\frac{1}{2}\left|u_{t}\right|^{2}+\frac{1}{2}\left|\frac{x}{|x|} u+\nabla u\right|^{2}\right), \\
\left|v_{t}(v+x \cdot \nabla v)\right| & \leq-T\left(\frac{1}{2}\left|v_{t}\right|^{2}+\frac{1}{2}\left|\frac{x}{|x|} v+\nabla v\right|^{2}\right) .
\end{aligned}
$$

Consequently,

$$
\begin{aligned}
J & \geq-T \int_{D_{T}} \frac{1}{2} F \mathrm{~d} x-T \int_{D_{T}}\left(\frac{1}{2}|\nabla u|^{2}-\frac{1}{2}\left|\nabla u+\frac{x}{|x|^{2}} u\right|^{2}+\frac{1}{2}|\nabla v|^{2}-\frac{1}{2}\left|\nabla v+\frac{x}{|x|^{2}} v\right|^{2}\right) \mathrm{d} x \\
& =|T| \int_{D_{T}} \frac{1}{2} F \mathrm{~d} x+T\left\{\int_{D_{T}}\left(u \frac{x}{|x|^{2}} \cdot \nabla u+v \frac{x}{|x|^{2}} \cdot \nabla v\right) \mathrm{d} x+\frac{1}{2} \int_{D_{T}}\left(\frac{u^{2}}{|x|^{2}}+\frac{v^{2}}{|x|^{2}}\right) \mathrm{d} x\right\} .
\end{aligned}
$$

Using integration by parts as before, we find that

$$
\begin{aligned}
& \int_{D_{T}} u \frac{x}{|x|^{2}} \cdot \nabla u \mathrm{~d} x+\frac{1}{2} \int_{D_{T}} \frac{u^{2}}{|x|^{2}} \mathrm{~d} x=\frac{1}{2} \int_{\partial D_{T}} \frac{u^{2}}{-T} \mathrm{~d} \sigma, \\
& \int_{D_{T}} v \frac{x}{|x|^{2}} \cdot \nabla v \mathrm{~d} x+\frac{1}{2} \int_{D_{T}} \frac{v^{2}}{|x|^{2}} \mathrm{~d} x=\frac{1}{2} \int_{\partial D_{T}} \frac{v^{2}}{-T} \mathrm{~d} \sigma,
\end{aligned}
$$

which yields

$$
J>|T| \int_{D_{T}} \frac{1}{2} F \mathrm{~d} x-\frac{1}{2} \int_{\partial D_{T}}\left(u^{2}+v^{2}\right) \mathrm{d} \sigma .
$$

Combining this with (3.10) and (3.11), we see that

$$
\begin{align*}
& |T| \int_{D_{T}} \frac{1}{2} F \mathrm{~d} x \\
\leq & C T^{4}+\frac{1}{\sqrt{2}} \int_{M_{T}^{0}}|t|\left(\left|\frac{x}{|x|} \cdot \nabla u-u_{t}+\frac{u}{|x|}\right|^{2}+\left|\frac{x}{|x|} \cdot \nabla v-v_{t}+\frac{v}{|x|}\right|^{2}\right) \mathrm{d} \sigma \\
\leq & C T^{4}+|T| \int_{M_{T}^{0}}\left(\left|\frac{x}{|x|} \cdot \nabla u-u_{t}\right|^{2}+\left|\frac{x}{|x|} \cdot \nabla v-v_{t}\right|^{2}\right) \mathrm{d} \sigma+\int_{M_{T}^{0}} \frac{u^{2}+v^{2}}{|t|} \mathrm{d} \sigma . \tag{3.12}
\end{align*}
$$

By (3.5), the second last term can be bounded by $|T| \operatorname{Flux}\left(u, v ; M_{T}^{0}\right)$, and the last term can also be controlled by the energy flux. In fact, if we use (H2) and Hölder's inequality, then we have

$$
\begin{aligned}
\int_{M_{T}^{0}} \frac{u^{2}+v^{2}}{|t|} \mathrm{d} \sigma & =\int_{M_{T}^{0}} \frac{u^{2}}{|t|} \mathrm{d} \sigma+\int_{M_{T}^{0}} \frac{v^{2}}{|t|} \mathrm{d} \sigma \\
& \leq\left(\int_{M_{T}^{0}}|t|^{-\frac{3}{2}} \mathrm{~d} \sigma\right)^{\frac{2}{3}}\left[\left(\int_{M_{T}^{0}} u^{6} \mathrm{~d} \sigma\right)^{\frac{1}{3}}+\left(\int_{M_{T}^{0}} v^{6} \mathrm{~d} \sigma\right)^{\frac{1}{3}}\right] \\
& \leq 2|T|\left[\int_{M_{T}^{0}} C_{0}\left(1+\frac{1}{2} F\right) \mathrm{d} \sigma\right]^{\frac{1}{3}} \\
& \leq 2|T|\left[C_{0} \operatorname{Flux}\left(u, v ; M_{T}^{0}\right)\right]^{\frac{1}{3}}+2|T|\left(\frac{4 \pi}{3} C_{0}|T|^{3}\right)^{\frac{1}{3}}
\end{aligned}
$$

If we plug in our estimates for the last two terms into (3.12), we conclude for small $|T|$ that

$$
\begin{aligned}
\int_{D_{T}} \frac{1}{2} F \mathrm{~d} x & \leq C|T|^{3}+\operatorname{Flux}\left(u, v ; M_{T}^{0}\right)+2\left[C_{0} \operatorname{Flux}\left(u, v ; M_{T}^{0}\right)\right]^{\frac{1}{3}}+2\left(\frac{4 \pi}{3} C_{0}\right)^{\frac{1}{3}}|T| \\
& \leq C\left[|T|+\operatorname{Flux}\left(u, v ; M_{T}^{0}\right)+\left(\operatorname{Flux}\left(u, v ; M_{T}^{0}\right)\right)^{\frac{1}{3}}\right] .
\end{aligned}
$$

This finally gives us the result since $\operatorname{Flux}\left(u, v ; M_{T}^{0}\right) \rightarrow 0$ as $T \nearrow 0$.
To finish the proof of the global existence theorem, we are just left with showing that the kinetic energy can not concentrate.

Proposition 3.2. Let $k=5$ and let $(u, v)$ be as in Proposition 1.3. Then

$$
\begin{equation*}
\lim _{t / T_{*}} \frac{1}{2} \int_{\left|x-x_{0}\right|<T_{*}-t}\left(\left|u^{\prime}\right|^{2}+\left|v^{\prime}\right|^{2}\right) \mathrm{d} x=0 \tag{3.13}
\end{equation*}
$$

Proof. From the assumptions (H2) and (H4), the non-concentrate of the potential energy from semi-linearity $F$

$$
\lim _{t>T_{*}} \frac{1}{2} \int_{\left|x-x_{0}\right|<T_{*}-t} F \mathrm{~d} x=0 .
$$

is equivalent to

$$
\lim _{t>T_{*}} \int_{\left|x-x_{0}\right|<T_{*}-t}\left(|u|^{6}+|v|^{6}\right) \mathrm{d} x=0
$$

The proof of Proposition 1.3 shows that this in turn implies that, for backward light cone through $\left(x_{0}, T_{*}\right)$ we have

$$
\begin{equation*}
u, v \in L_{t}^{4} L_{x}^{12}\left(\Lambda\left(0 ; 0, T_{*}\right)\right) \tag{3.14}
\end{equation*}
$$

Applying (1.9) to

$$
\left\{\begin{array}{l}
u_{t t}^{\prime}-\Delta u^{\prime}=-\left(F_{1} u\right)^{\prime} \\
v_{t t}^{\prime}-\Delta v^{\prime}=-\left(F_{2} v\right)^{\prime}
\end{array}\right.
$$

and arguing as in the proof of Proposition 1.3 gives for $J_{0}=\Lambda\left(0 ; t_{0}, s\right)$

$$
\begin{aligned}
& \sup _{t_{0} \leq t \leq T_{*}}\left(\int_{\left|x-x_{0}\right|<T_{*}-t}|u|^{6} \mathrm{~d} x\right)^{\frac{1}{6}}+\sup _{t_{0} \leq t \leq T_{*}}\left(\int_{\left|x-x_{0}\right|<T_{*}-t}|v|^{6} \mathrm{~d} x\right)^{\frac{1}{6}} \\
& =\left\|u^{\prime}\right\|_{L_{t}^{\infty} L_{x}^{6}\left(J_{0}\right)}+\left\|v^{\prime}\right\|_{L_{t}^{\infty} L_{x}^{6}\left(J_{0}\right)} \\
& \leq C \sum_{|\alpha|=2}\left\|\partial^{\alpha} u\left(\cdot, t_{0}\right)\right\|_{L^{2}\left(\mathbb{R}^{3}\right)}+C\left\|\left(F_{1} u\right)^{\prime}\right\|_{L_{t}^{1} L_{x}^{2}\left(J_{0}\right)} \\
& +C \sum_{|\alpha|=2}\left\|\partial^{\alpha} v\left(\cdot, t_{0}\right)\right\|_{L^{2}\left(\mathbb{R}^{3}\right)}+C\left\|\left(F_{2} v\right)^{\prime}\right\|_{L_{t}^{1} L_{x}^{2}\left(J_{0}\right)} \\
& \leq C \sum_{|\alpha|=2}\left(\left\|\partial^{\alpha} u\left(\cdot, t_{0}\right)\right\|_{L^{2}\left(\mathbb{R}^{3}\right)}+\left\|\partial^{\alpha} v\left(\cdot, t_{0}\right)\right\|_{L^{2}\left(\mathbb{R}^{3}\right)}\right) \\
& +C^{\prime}\left(1+\left\||u|^{4} u^{\prime}\right\|_{L_{t}^{1} L_{x}^{2}\left(J_{0}\right)}+\left\||u|^{4} v^{\prime}\right\|_{L_{t}^{1} L_{x}^{2}\left(J_{0}\right)}+\left\||v|^{4} u^{\prime}\right\|_{L_{t}^{1} L_{x}^{2}\left(J_{0}\right)}+\left\||v|^{4} v^{\prime}\right\|_{L_{t}^{1} L_{x}^{2}\left(J_{0}\right)}\right) \\
& \leq C \sum_{|\alpha|=2}\left(\left\|\partial^{\alpha} u\left(\cdot, t_{0}\right)\right\|_{L^{2}\left(\mathbb{R}^{3}\right)}+\left\|\partial^{\alpha} v\left(\cdot, t_{0}\right)\right\|_{L^{2}\left(\mathbb{R}^{3}\right)}\right) \\
& +C^{\prime}+C^{\prime}\left(\|u\|_{L_{t}^{4} L_{x}^{12}\left(J_{0}\right)}^{4}\left\|u^{\prime}\right\|_{L_{t}^{\infty} L_{x}^{L}\left(J_{0}\right)}+\|u\|_{L_{t}^{4} L_{x}^{12}\left(J_{0}\right)}^{4}\right) v^{\prime} \|_{L_{t}^{\infty} L_{x}^{6}\left(J_{0}\right)} \\
& \left.+\|v\|_{L_{t}^{4} L_{x}^{12}\left(J_{0}\right)}^{4}\left\|u^{\prime}\right\|_{L_{t}^{\infty} L_{x}^{6}\left(J_{0}\right)}+\|v\|_{L_{t}^{4} L_{x}^{12}\left(J_{0}\right)}^{4}\left\|v^{\prime}\right\|_{L_{t}^{\infty} L_{x}^{6}\left(J_{0}\right)}\right) \\
& =C\left(t_{0}\right)+C^{\prime}\left(\|u\|_{L_{t}^{4} L_{x}^{12}\left(J_{0}\right)}^{4}\left\|u^{\prime}\right\|_{L_{t}^{\infty} L_{x}^{6}\left(J_{0}\right)}+\|u\|_{L_{t}^{4} L_{x}^{L_{x}^{2}}\left(J_{0}\right)}^{4}\left\|v^{\prime}\right\|_{L_{t}^{\infty} L_{x}^{6}\left(J_{0}\right)}\right. \\
& \left.+\|v\|_{L_{t}^{4} L_{x}^{12}\left(J_{0}\right)}^{4}\left\|u^{\prime}\right\|_{L_{t}^{\infty} L_{x}^{6}\left(J_{0}\right)}+\|v\|_{L_{t}^{4} L_{x}^{12}\left(J_{0}\right)}^{4}\left\|v^{\prime}\right\|_{L_{t}^{\infty} L_{x}^{6}\left(J_{0}\right)}\right),
\end{aligned}
$$

The result (3.14) implies that the $L_{t}^{4} L_{x}^{12}\left(J_{0}\right)$ norm goes to zero as $t_{0} \rightarrow T_{*}$. We therefore conclude that, if $t_{0}$ is close to $T_{*}$,

$$
\sup _{t_{0} \leq t<T_{*}}\left(\int_{\left|x-x_{0}\right|<T_{*}-t}\left|u^{\prime}\right|^{6} \mathrm{~d} x\right)^{\frac{1}{6}}+\sup _{t_{0} \leq t<T_{*}}\left(\int_{\left|x-x_{0}\right|<T_{*}-t}\left|v^{\prime}\right|^{6} \mathrm{~d} x\right)^{\frac{1}{6}} \leq 2 C\left(t_{0}\right)
$$

But the application of Hölder's inequality shows that this leads to

$$
\begin{aligned}
& \left(\int_{\left|x-x_{0}\right|<T_{*}-t}\left|u^{\prime}\right|^{2} \mathrm{~d} x\right)^{\frac{1}{2}} \leq 2 C\left(t_{0}\right)\left(\frac{4 \pi}{3}\left(T_{*}-t\right)^{3}\right)^{\frac{1}{3}} \\
& \left(\int_{\left|x-x_{0}\right|<T_{*}-t}\left|v^{\prime}\right|^{2} \mathrm{~d} x\right)^{\frac{1}{2}} \leq 2 C\left(t_{0}\right)\left(\frac{4 \pi}{3}\left(T_{*}-t\right)^{3}\right)^{\frac{1}{3}}
\end{aligned}
$$

Hence we obtained the desired result (3.13). This completes the proof of Proposition 3.2.

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[^0]:    *Corresponding author. Email address: wuhaigen@gmail.com (H. Wu)

