## A NEW ALGORITHM FOR COMPUTING THE INVERSE AND GENERALIZED INVERSE OF THE SCALED FACTOR CIRCULANT MATRIX\*

Zhaolin Jiang

School of Science, Xi'an Jiaotong University, Xi'an 710049, China, and Department of Mathematics, Linyi Teachers College, Linyi 276005, China Email: jzh1208@sina.com Zongben Xu School of Science, Xi'an Jiaotong University, Xi'an 710049, China

Email: zbxu@mail.xjtu.edu.cn

## Abstract

A new algorithm for finding the inverse of a nonsingular scaled factor circulant matrix is presented by the Euclid's algorithm. Extension is made to compute the group inverse and the Moore-Penrose inverse of the singular scaled factor circulant matrix. Numerical examples are presented to demonstrate the implementation of the proposed algorithm.

Mathematics subject classification: 15A21, 65F15. Key words: Scaled factor circulant matrix, Inverse, Group inverse, Moore-Penrose inverse.

## 1. Introduction

Circulant matrices, as an important class of special matrices, have a wide range of interesting applications [12–19]. They have in recent years been applied in many areas, see, e.g., [2, 3, 6, 10, 11, 15, 17]. Scaled circulant permutation matrices and the matrices that commute with them are natural extensions of this well-studied class, see, e.g., [1, 20–23]. In particular, it will be seen that *r*-circulant matrices [10, 11] are precisely those matrices commuting with the scaled circulant permutation matrix.

This paper presents an efficient algorithm to compute the inverse of a nonsingular scaled factor circulant matrix or to compute the group inverse and Moore-Penrose inverse of the circulant matrix when it is singular. The algorithm has small computational complexity. It is a notable character of the algorithm that the singularity of the scaled factor circulant matrix need not be priori known.

We define  $\mathcal{R}$  as the scaled circulant permutation matrix, that is,

$$\mathcal{R} = \begin{pmatrix} 0 & d_1 & 0 & \dots & 0 & 0 \\ 0 & 0 & d_2 & \dots & 0 & 0 \\ \dots & \dots & \dots & \dots & \dots & \dots \\ 0 & 0 & 0 & \dots & 0 & d_{n-1} \\ d_n & 0 & 0 & \dots & 0 & 0 \end{pmatrix}_{n \times n}$$
(1.1)

This paper deals with the case where  $\mathcal{R}$  is nonsingular ( $d_i \neq 0$  and fixed).

It is easily verified that the polynomial  $g(x) = x^n - d_1 d_2 \dots d_n$  is both the minimal polynomial and the characteristic polynomial of the matrix  $\mathcal{R}$ . In addition,  $\mathcal{R}$  is nondergatory.

<sup>\*</sup> Received August 10, 2006 / Revised version received April 23, 2007 / Accepted May 15, 2007 /

A New Algorithm for Computing the Inverse of the Scaled Factor Circulant Matrix

Moreover,  $\mathcal{R}$  is normal if and only if  $|d_1| = |d_2| = \cdots = |d_n|$ , where  $|d_i|, i = 1, \cdots, n$  denote the modulus of the complex number  $d_i, i = 1, \cdots, n$ .

**Definition 1.1.** An  $n \times n$  matrix A over  $\mathbb{C}$  is called a scaled factor circulant matrix if A commutes with  $\mathcal{R}$ , that is,

$$A\mathcal{R} = \mathcal{R}A,\tag{1.2}$$

where  $\mathcal{R}$  is given in (1.1).

Let  $\mathcal{R}SFCM_n$  be the set of all complex  $n \times n$  matrices which commute with  $\mathcal{R}$ . In the following, with  $A = \operatorname{scacirc}_{\mathcal{R}}(a_0, a_1, \cdots, a_{n-1})$  we denote the scaled factor circulant matrix A whose first row is  $(a_0, a_1, \ldots, a_{n-1})$ . Remark that the first row of A completely defines the matrix. Indeed, since  $\mathcal{R}$  is nonderogatory, Eq. (1.2) is fulfilled if and only if  $A = f(\mathcal{R})$  for some polynomial f. Furthermore,  $\mathcal{R}SFCM_n$  is a vector space of dimension n, and there is a clear one-to-one correspondence between the polynomials of degree at most n-1 and the numbers  $a_0, \cdots, a_{n-1}$ .

For an  $m \times n$  matrix A, any solution to the matrix equation AXA = A is called a *generalized* inverse of A. In addition, if X satisfies X = XAX, then A and X are said to be semi-inverses, see, e.g., [2].

In this paper we only consider square matrices A. In [8, p.51] the smallest positive integer k for which rank $(A^{k+1})$ =rank $(A^k)$  holds is called the *index* of A. If A has index 1, the generalized inverse X of A is called the *group inverse*  $A^{\#}$  of A. Clearly, A and X are group inverses if and only if they are semi-inverses and AX = XA.

In [4, 5] a semi-inverse X of A was considered in which the nonzero eigenvalues of X are the reciprocals of the nonzero eigenvalue of A. These matrices were called *spectral inverses*. It was shown in [5] that a nonzero matrix A has a unique spectral inverse,  $A^s$ , if and only if A has index 1: when  $A^s$  is the group inverse  $A^{\#}$  of A.

## 2. The Properties of the Scaled Factor Circulant Matrix

**Lemma 2.1.** ([1]) If  $\mathcal{R}$  is a scaled circulant permutation matrix, and if k is a positive integer, then  $\mathcal{R}^k = D^{(k)}C^k$ , where  $D^{(k)}$  is the diagonal matrix whose (j,j) entry is  $\prod_{t=j}^{j+k-1} d_t$  for  $1 \leq j \leq n$  and  $C = circ(0, 1, 0, \dots, 0)$  is the circulant permutation. Furthermore,

$$\mathcal{R}^n = (\prod_{j=1}^n d_j) I_n, \quad \det \mathcal{R} = (-1)^{n-1} \prod_{j=1}^n d_j.$$

Let  $\omega = \exp(\frac{2\pi i}{n})$  be a primitive *n*th root of unity. Then  $\omega_j = d\omega^j$ ,  $j = 0, 1, \dots, n-1$  are the distinct roots of g(x), where  $g(x) = x^n - d_1 d_2 \cdots d_n$ , and

$$d = (\prod_{t=1}^{n} d_t)^{\frac{1}{n}} \neq 0.$$
(2.1)

Let F be the  $n \times n$  unitary Fourier matrix such that

$$F_{ij} = \frac{1}{\sqrt{n}} \omega^{(i-1)(j-1)} \quad \text{for } 1 \le i, \ j \le n.$$
(2.2)

Let

$$\Delta = \operatorname{diag}(\delta_1, \delta_2, \cdots, \delta_n), \tag{2.3}$$