

# $T^*$ -extension of Lie Supertriple Systems

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**Abstract:** In this article, we study the Lie supertriple system (LSTS)  $T$  over a field  $\mathbb{K}$  admitting a nondegenerate invariant supersymmetric bilinear form (call such a  $T$  metrisable). We give the definition of  $T_\omega^*$ -extension of an LSTS  $T$ , prove a necessary and sufficient condition for a metrised LSTS  $(T, \phi)$  to be isometric to a  $T^*$ -extension of some LSTS, and determine when two  $T^*$ -extensions of an LSTS are “same”, i.e., they are equivalent or isometrically equivalent.

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## 1 Introduction

A Lie (super)triple system over a field  $\mathbb{K}$  is called pseudo-metrisable if it admits an invariant nondegenerate bilinear form, and if further, the bilinear form can be chosen to be (super)symmetric, then  $T$  is called metrisable. Recently, metrisable Lie (super)triple systems have attracted a lot of attention due to its applications in the areas of mathematics and physics (see, for example, [1–6]).

The method of  $T^*$ -extension of Lie algebras was first introduced by Bordemann<sup>[7]</sup> in 1997 and this method is an important method for studying algebraic structures. In our early paper, we investigated the  $T^*$ -extension of Lie triple systems (see [6]). This paper is devoted to transfer the  $T^*$ -extension method to Lie supertriple systems.

Throughout this paper, all Lie supertriple systems considered are assumed to be of finite dimension over a field  $\mathbb{K}$ .

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## 2 Lie Supertriple Systems

In this section, we first briefly sketch the notion of a (pseudo-)metrisable Lie supertriple system.

Let  $V = V_{\bar{0}} \oplus V_{\bar{1}}$  be a  $\mathbf{Z}_2$ -graded space over  $\mathbb{K}$ , where  $V_{\bar{0}}$  and  $V_{\bar{1}}$  are called bosonic and fermionic space, respectively, in physics literature. We denote the degree by

$$\deg(x) = \begin{cases} 0, & \text{if } x \in V_{\bar{0}}; \\ 1, & \text{if } x \in V_{\bar{1}}. \end{cases}$$

and write  $(-1)^{xy} := (-1)^{\deg(x)\deg(y)}$ .

Any element considered in this article is always assumed to be homogeneous, i.e., either  $x \in V_{\bar{0}}$  or  $x \in V_{\bar{1}}$ .

Notice that the associate algebra  $\text{End}V$  is a superalgebra  $\text{End}V = \text{End}_{\bar{0}}V \oplus \text{End}_{\bar{1}}V$ ,

$$\text{End}_{\alpha}V = \{a \in \text{End}V \mid aV_s \subseteq V_{s+\alpha}, s = \bar{0}, \bar{1}\}, \quad \alpha = \bar{0}, \bar{1}.$$

**Definition 2.1** *A Lie supertriple system (LSTS) is a  $\mathbf{Z}_2$ -graded space  $T = T_{\bar{0}} \oplus T_{\bar{1}}$  over  $\mathbb{K}$  with a trilinear composition  $[\cdot, \cdot, \cdot]$ , satisfying the following conditions:*

- (1)  $\deg([xyz]) = (\deg(x) + \deg(y) + \deg(z)) \pmod{2}$ ;
- (2)  $[yxz] = -(-1)^{xy}[xyz]$ ;
- (3)  $(-1)^{xz}[xyz] + (-1)^{yx}[yzx] + (-1)^{zy}[zxy] = 0$ ;
- (4)  $[uv[xyz]] = [[uvx]yz] + (-1)^{(u+v)x}[x[uvy]z] + (-1)^{(u+v)(x+y)}[xy[uvz]]$ .

An ideal of an LSTS  $T$  is a graded subspace  $I$  for which  $[I, T, T] \subseteq I$ . Moreover, if  $[TII] = 0$ , then  $I$  is called an abelian ideal of  $T$ .  $T$  is called abelian if it is an abelian ideal of itself. For any graded subspace  $V$  in  $T$ , the centralizer  $Z_T(V)$  of  $V$  in  $T$  is defined by

$$Z_T(V) = \{x \in T \mid [xvt] = [xtv] = 0, \text{ for all } t \in T, v \in V\}.$$

In particular,  $Z_T(T)$  is called the center of  $T$  and denoted simply by  $Z(T)$ . If  $T$  is an LSTS, define the lower central series for  $T$  by  $T^0 := T$  and  $T^{n+1} := [T^n TT]$  for  $n \geq 0$ .  $T$  is called nilpotent (of nilindex  $m$ ) if there is a (smallest) positive integer  $m$  such that  $T^m = 0$ . Put  $T^{(0)} := T$  and  $T^{(n+1)} := [T^{(n)} TT^{(n)}]$ . Then  $T$  is called solvable (of length  $k$ ) if there is a (smallest) positive integer  $k$  such that  $T^{(k)} = 0$ .

**Definition 2.2** *If an LSTS  $T$  admits a nondegenerate bilinear form  $b$  satisfying conditions*

- (1)  $b(x, y) = 0$  unless  $d(x) = d(y)$ ; (consistence)
- (2)  $b([x, y, u], v) = -(-1)^{(x+y)u}b(u, [x, y, v])$ , (invariance)

*then we call  $T$  pseudo-metrisable and the pair  $(T, b)$  a pseudo-metrised LSTS. If, in addition,  $b$  satisfies also;*

- (3)  $b(x, y) = (-1)^{xy}b(y, x)$ , (supersymmetry)

*then we call  $T$  metrisable and the pair  $(T, b)$  a metrised LSTS.*

**Proposition 2.1**<sup>[1]</sup> *The following conditions are equivalent:*

- (1)  $b([x, y, u], v) = -(-1)^{(x+y)u}b(u, [x, y, v])$ ;

- (2)  $b([x, y, u], v) = -(-1)^{(u+v)y}b(x, [u, v, y]);$   
(3)  $b(x, [y, u, v]) = (-1)^{xy+uv}b(y, [x, v, u]).$

Define multiplication operators  $L(\cdot, \cdot)$ ,  $P(\cdot, \cdot)$ ,  $R(\cdot, \cdot)$  on  $T$  by

$$L(x, y)z := [x, y, z], \quad P(x, y)z := (-1)^{yz}[xzy], \quad R(x, y)z := (-1)^{(x+y)z}[z, x, y].$$

**Definition 2.3** For  $x, y, z \in T$ ,  $f \in T^*$ , define the following dual multiplication operators on  $T^*$  by

- (1)  $(L^*(x, y)f)(z) := (-1)^{xy}f(L(y, x)(z));$   
(2)  $(P^*(x, y)f)(z) := (-1)^{xy}f(P(y, x)(z));$   
(3)  $(R^*(x, y)f)(z) := (-1)^{xy}f(R(y, x)(z)).$

Noticing that for any  $x, y, z \in T$ ,  $f \in T^*$ ,

$$\begin{aligned} L^*(x, y)f(z) &= (-1)^{xy}f([yxz]) = (-1)^{(x+y)z}f([zxy]) - (-1)^{xy+(x+y)z}f([zyx]) \\ &= f(R(x, y)(z)) - (-1)^{xy}f(R(y, x)(z)) = ((-1)^{xy}R^*(y, x) - R^*(x, y))f(z) \end{aligned}$$

and

$$\begin{aligned} (P^*(x, y)f)(z) &= (-1)^{xy}f(P(y, x)(z)) = (-1)^{x(y+z)}f([yzx]) \\ &= -(-1)^{xy+xz+yz}f([zyx]) = -(-1)^{xy}f(R(y, x)(z)) = (-R^*(xy)f)(z), \end{aligned}$$

we have

$$L^*(x, y) = (-1)^{xy}R^*(y, x) - R^*(x, y) \quad \text{and} \quad P^*(x, y) = -R^*(x, y). \quad (2.1)$$

**Definition 2.4** A trilinear mapping  $\omega : T \times T \times T \rightarrow T^*$  is called a 3-supercocycle if it satisfies the following conditions:

- (1)  $\omega(y, x, z) = -(-1)^{xy}\omega(x, y, z);$   
(2)  $(-1)^{xz}\omega(x, y, z) + (-1)^{yx}\omega(y, z, x) + (-1)^{zy}\omega(z, x, y) = 0;$   
(3)  $(-1)^{(u+v)(x+y+z)}L^*(u, v)\omega(x, y, z) + \omega(u, v, [xyz])$   
 $= R^*(y, z)\omega(u, v, x) + (-1)^{xy}P^*(x, z)\omega(u, v, y) + (-1)^{(x+y)z}L^*(x, y)\omega(u, v, z)$   
 $+ \omega([uvx], y, z) + (-1)^{(u+v)x}\omega(x, [uvy], z) + (-1)^{(u+v)(x+y)}\omega(x, y, [uvz]).$

### 3 $T_\omega^*$ -extension

Recall that if  $\phi$  is a bilinear form on a vector space  $V$ , and  $W$  is a subspace of  $V$ , then the right orthogonal space (resp. left orthogonal space) of  $W$  is given by  $W^\perp := \{v \in V \mid \phi(w, v) = 0, \forall w \in W\}$  (resp.  ${}^\perp W := \{v \in V \mid \phi(v, w) = 0, \forall w \in W\}$ ). The intersection of  ${}^\perp V$  and  $V^\perp$  is called the kernel  $N_\phi$  of  $\phi$ . The following lemma gives the basic results of pseudo-metrised LSTS.

**Lemma 3.1** Let  $(T, \phi)$  be a pseudo-metrised LSTS over a field  $\mathbb{K}$ , and  $V$  be an arbitrary vector subspace of  $T$ .

- (i) Let  $I$  be an ideal of  $T$ . Then  ${}^\perp I$  and  $I^\perp$  are ideals of  $T$  and  $I^\perp, {}^\perp I \subset Z_T(I);$   
(ii) For arbitrary subspace  $V$ ,  $Z_T(V) = [VTT]^\perp = {}^\perp [VTT]$ . If  $V$  is an ideal, then  $Z_T(V)$  is an ideal;  
(iii) In particular,  $Z(T) = (T^{(1)})^\perp = {}^\perp (T^{(1)})$  for  $T^{(1)} = [TTT]$ .

Now we consider the transfer of invariant bilinear forms from one LSTS to another. Let  $T$  (resp.  $T'$ ) be an LSTS over a field  $\mathbb{K}$ ,  $f$  (resp.  $g$ ) be an invariant bilinear form on  $T$  (resp.  $T'$ ), and  $m : T \rightarrow T'$  be a homomorphism of LSTS. Then we have the following lemma.

**Lemma 3.2** *Under the above assumptions, we have*

- (i) *The pull back  $m^*g$  of  $g$  is again an invariant bilinear form on  $T$ ;*
- (ii) *Suppose that  $m$  is surjective and  $\ker m$  is contained in the kernel of  $f$ . Then the projection  $f^m$  of  $f$  is an invariant bilinear form on  $T'$ ;*
- (iii) *If  $U$  is a subsystem of  $T$ , then  $U \cap U^\perp$  is an ideal of  $U$ . Let  $p : U \rightarrow U/(U \cap U^\perp)$  be the projection and  $f_U$  be the restriction of  $f$  to  $U \times U$ . Then the projection  $(f_U)^p$  is a nondegenerate invariant bilinear form on the factor system  $U/(U \cap U^\perp)$ ;*
- (iv) *The bilinear form  $f \perp g$  is invariant on the direct sum  $T \oplus T'$ . Moreover,  $f \perp g$  is nondegenerate if and only if  $f$  and  $g$  are nondegenerate.*

The proofs of both Lemmas 3.1 and 3.2 are similar to that of Lie triple systems, which can be found in [6].

Now we generalize the notion of  $T^*$ -extension of a Lie triple system to that of a Lie supertriple system.

**Definition 3.1** *Let  $T$  be an LSTS,  $T^*$  be the dual space of  $T$ , and  $\omega$  be a 3-supercocycle. Define a ternary multiplication on  $T_\omega^*T = T \oplus T^*$  by*

$$\begin{aligned} & [x + f, y + g, z + h] \\ &= [xyz]_T + \omega(x, y, z) + (-1)^{(x+y)z} L^*(x, y)h + (-1)^{xy} P^*(x, z)g + R^*(y, z)f \end{aligned}$$

*for all  $x, y, z \in T$ , and  $f, g, h \in T^*$ , where  $x + f$  (resp.  $y + g, z + h$ ) is homogeneous of degree  $\deg(x)$  (resp.  $\deg(y), \deg(z)$ ), and  $[xyz]_T$  is the Lie superbracket in  $T$ .*

**Lemma 3.3** *Under the above definition, if  $\deg(\omega) = 0$ , then  $T_\omega^*T$  is an LSTS, which is called the  $T^*$ -extension of the LSTS  $T$  by means of  $\omega$ . In particular, if  $\omega = 0$ , then  $T_0^*T$  is called the trivial  $T^*$ -extension of  $T$ .*

*Proof.* Here we only consider the last equation in the definition of LSTS. We need to verify

$$\begin{aligned} & [u + i, v + j, [x + f, y + g, z + h]] \\ &= [[u + i, v + j, x + f], y + g, z + h] + (-1)^{(u+v)x} [x + f, [u + i, v + j, y + g], z + h] \\ & \quad + (-1)^{(u+v)(x+y)} [x + f, y + g, [u + i, v + j, z + h]] \end{aligned}$$

for  $u, v, x, y, z \in T$ ,  $i, j, f, g, h \in T^*$ . Expand this equation by Definition 3.1. Then all items consist of the ternary compositions in  $T$  and the 3-supercocycle  $\omega$  are canceled by the definitions of an LSTS and a 3-supercocycle. The items consisting of  $h$  reads

$$\begin{aligned} & (-1)^{(x+y)z+(u+v)(x+y+z)} L^*(u, v)L^*(x, y)h \\ &= (-1)^{(u+v+x+y)z} L^*([uvx], y)h + (-1)^{(u+v)x} (-1)^{(u+v+x+y)z} L^*(x, [uvy])h \\ & \quad + (-1)^{(u+v)(x+y)+(u+v)z+(x+y)(u+v+z)} L^*(x, y)L^*(u, v)h, \end{aligned}$$

that is,

$$\begin{aligned} & h((-1)^{(u+v)(x+y)}L(y, x)L(v, u)) \\ &= h(-(-1)^{(u+v)y}L(y, [vux]) - L([vuy], x) + L(v, u)L(y, x)). \end{aligned}$$

The above equation holds due to the last equation in the definition of an LSTS. Other items consisting of  $i, j, f$  or  $g$  can be verified similarly. This completes the proof.

By this lemma, we always suppose that the 3-supercocycle  $\omega$  satisfies  $\deg(\omega) = 0$ .

It is clear from the definition that the subspace  $T^*$  is an abelian ideal of  $T_\omega^*T$  and  $T$  is isomorphic to the factor supertriple system  $T_\omega^*T/T^*$ . Moreover, consider the following consistent supersymmetric bilinear form  $q_T$  on  $T_\omega^*T$  defined for all  $x, y \in T, f, g \in T^*$  by

$$q_T(x + f, y + g) = f(y) + (-1)^{xy}g(x). \quad (3.1)$$

We then have the following lemma.

**Lemma 3.4** *Let  $T, T^*, \omega$  and  $q_T$  be as above. Then  $q_T$  is a nondegenerate supersymmetric bilinear form on  $T_\omega^*T$  and the following conditions are equivalent:*

- (1)  $q_T$  is invariant;
- (2)  $\omega(x, y, u)(v) = -(-1)^{uv}\omega(x, y, v)(u)$ ;
- (3)  $\omega(x, y, u)(v) = -(-1)^{(u+v)(x+y)+xy}\omega(u, v, y)(x)$ ;
- (4)  $\omega(y, u, v)(x) = (-1)^{(y+u+v)x+(y+u)v+yu}\omega(x, v, u)(y)$ .

Hence  $(T_\omega^*, q_T)$  is a metrised LSTS if and only if  $\omega$  satisfies one of (2)–(4).

*Proof.* If  $x + f$  is orthogonal to all elements of  $T_\omega^*T$ , then, in particular,  $f(y) = 0$  for all  $y \in T$  and  $g(x) = 0$  for all  $g \in T^*$ , which implies that  $f = 0$  and  $x = 0$ . So the supersymmetric bilinear form  $q_T$  is nondegenerate.

Now we consider the invariant property. Let  $x, y, u, v \in T$  and  $f, g, p, q \in T^*$ . Then we have

$$\begin{aligned} & q_T([x + f, y + g, u + p], v + q) \\ &= q_T([xyu] + \omega(x, y, u) + (-1)^{(x+y)u}L^*(x, y)p + (-1)^{xy}P^*(x, u)g + R^*(y, u)f, v + q) \\ &= \omega(x, y, u)(v) + (-1)^{(x+y)u+xy}P(L(y, x)v) + (-1)^{x(y+u)}g(P(u, x)v) + (-1)^{yu}f(R(u, y)v) \\ &\quad + (-1)^{(x+y+u)v}q([xyu]) \\ &= \omega(x, y, u)(v) + (-1)^{(x+y)u+xy}P([yxv]) + (-1)^{x(y+u+v)}g([uvx]) + (-1)^{yu+(y+u)v}f([vuy]) \\ &\quad + (-1)^{(x+y+u)v}q([xyu]). \end{aligned}$$

On the other hand,

$$\begin{aligned} & -(-1)^{(x+y)u}q_T(u + p, [x + f, y + g, v + q]) \\ &= -(-1)^{(x+y)u}q_T(u + p, [xyv] + \omega(x, y, v) + (-1)^{(x+y)v}L^*(x, y)q \\ &\quad + (-1)^{xy}P^*(x, v)g + R^*(y, v)f) \\ &= -(-1)^{(x+y)u}P([xyv]) - (-1)^{uv}\omega(x, y, v)(u) - (-1)^{(x+y+u)v}(L^*(x, y)q)(u) \\ &\quad - (-1)^{xy+uv}(P^*(x, v)g)(u) - (-1)^{uv}(R^*(y, v)f)(u) \end{aligned}$$

$$\begin{aligned}
&= (-1)^{(x+y)u+xy}P([yxv]) - (-1)^{uv}\omega(x, y, v)(u) - (-1)^{(x+y+u)v+xy}q([yxu]) \\
&\quad - (-1)^{x(y+v+u)+uv}g([vux]) - (-1)^{y(u+v)}f([uvy]) \\
&= (-1)^{(x+y)u+xy}P([yxv]) - (-1)^{uv}\omega(x, y, v)(u) + (-1)^{(x+y+u)v}q([xyu]) \\
&\quad + (-1)^{x(y+v+u)}g([uvx]) + (-1)^{y(u+v)+uv}f([vuy]).
\end{aligned}$$

Comparing these results we get that  $q_T$  is invariant if and only if

$$\omega(x, y, u)(v) = -(-1)^{uv}\omega(x, y, v)(u).$$

In a similar way, by the equivalence condition of Proposition 2.1, we can obtain also that  $q_T$  is invariant if and only if

$$\omega(x, y, u)(v) = -(-1)^{(u+v)(x+y)+xy}\omega(u, v, y)(x)$$

and if and only if

$$\omega(y, u, v)(x) = (-1)^{(y+u+v)x+(y+u)v+yu}\omega(x, v, u)(y).$$

Thus the lemma is proved.

## 4 Metrisable LSTS

**Lemma 4.1** *Let  $(T, \phi)$  be a metrised LSTS of dimension  $n$  over a field  $\mathbb{K}$ , and  $I$  be an isotropic  $\frac{n}{2}$ -dimensional subspace of  $T$ . Then  $I$  is an ideal of  $T$  if and only if  $I$  satisfies  $I^{(1)} := [TII] = 0$ . Hence  $I$  is an ideal if and only if  $I$  is an abelian ideal of  $T$ .*

*Proof.* Since  $\dim I + \dim I^\perp = n$  it follows that  $I = I^\perp$ . If  $I$  is an ideal of  $T$ , then

$$\phi([TIT], I) = \phi([TIT], I^\perp) = 0.$$

Hence  $\phi(T, [TII]) = 0$ , and the non-degeneracy property of  $\phi$  implies  $I^{(1)} = [TII] = 0$ .

Conversely, if  $I^{(1)} = [TII] = 0$ , then

$$\phi(I, [ITT]) = \phi([ITI], T) = \phi([TII], T) = 0.$$

Hence  $[ITT] \subset I^\perp = I$ . This implies that  $I$  is an ideal of  $T$ .

**Theorem 4.1** *Let  $(T, \phi)$  be a metrised LSTS of dimension  $n$  over a field  $\mathbb{K}$  of characteristic not equal to two. Then  $(T, \phi)$  is isometric to a  $T^*$ -extension  $(T_\omega^*B, q_B)$  if and only if  $n$  is even and  $T$  contains an isotropic ideal  $I$  (i.e.,  $I \subset I^\perp$ ) of dimension  $\frac{n}{2}$ . In this case:  $B \cong T/I$ .*

*Proof.* Sufficiency. Since  $\dim B = \dim B^*$ , it is clear that  $\dim T_\omega^*B$  is even. Moreover, it is clear from the definition of the multiplication in Definition 3.1 that  $B^*$  is an isotropic ideal of half the dimension of  $T_\omega^*B$ .

Necessity. Suppose that  $I$  is an  $\frac{n}{2}$ -dimensional isotropic ideal of  $T$ . Let  $B$  denote the factor supertriple system  $T/I$  and  $p : T \rightarrow B$  the canonical projection. Now, since the characteristic  $\mathbb{K}$  is not equal to 2, we can choose an isotropic complementary vector subspace  $B_0$  to  $I$  in  $T$ , i.e.,  $T = B_0 \oplus I$  and  $B_0^\perp = B_0$ . Denote by  $p_0$  (resp.  $p_1$ ) the projection  $T \rightarrow B_0$  (resp.  $T \rightarrow I$ ) along  $I$  (resp. along  $B_0$ ). Moreover, let  $\phi^I$  denote the linear map  $I \rightarrow B^* : i \rightarrow (px \rightarrow \phi(i, x))$ . It is well-defined because  $\phi(I, I) = 0$ . Since  $\phi$  is

nondegenerate,  $I^\perp = I$ , and  $\dim I = \frac{n}{2} = \dim B$ . It follows that  $\phi^I$  is a linear isomorphism. Furthermore,  $\phi^I$  has the following intertwining property: Let  $x, y, z \in T$  and  $i \in I$ . Then

$$\begin{aligned} \phi^I([xyi])(pz) &= \phi([xyi], z) \\ &= -(-1)^{(x+y)i} \phi(i, [xyz]) \\ &= -(-1)^{(x+y)i} \phi^I(i)([px, py, pz]) \\ &= -(-1)^{(x+y)i+xy} L^*(py, px) \phi^I(i)(pz) \\ &= -(-1)^{(x+y)i} L^*(px, py) \phi^I(i)(pz). \end{aligned}$$

Hence after a completely analogous computation one has the following

$$\begin{cases} \phi^I([xyi]) = -(-1)^{(x+y)i} L^*(px, py) \phi^I(i), \\ \phi^I([xiy]) = (-1)^{ix} P^*(px, py) \phi^I(i), \\ \phi^I([ixy]) = R^*(px, py) \phi^I(i), \end{cases} \quad (4.1)$$

where  $x, y \in T$  and  $i \in I$ . We define the following trilinear map:

$$\omega : B \times B \times B \rightarrow B^* : (pb_0, pb'_0, pb''_0) \rightarrow \phi^I(p_1[b_0, b'_0, b''_0]),$$

where  $b_0, b'_0$  and  $b''_0$  are in  $B_0$ . This is well-defined since the restriction of the projection  $p$  to  $B_0$  is a linear isomorphism. Now, let  $m$  denote the following linear map

$$T \rightarrow B \oplus B^* : b_0 + i \rightarrow pb_0 + \phi^I(i),$$

where  $b_0 \in B$  and  $i \in I$ . Since  $p$  is restricted to  $B_0$  and  $\phi^I$  are linear isomorphisms, the map  $m$  is also a linear isomorphism. Moreover,  $m$  is an isomorphism of the metrised LSTS  $(T, \phi)$  to the  $T^*$ -extension  $(T_\omega^* B, q_B)$ . Indeed, let  $b_0, b'_0, b''_0 \in B$  and  $i, i', i'' \in I$ . Then

$$\begin{aligned} & m([(b_0 + i)(b'_0 + i')(b''_0 + i'')]) \\ &= m(p_0([b_0, b'_0, b''_0]) + p_1([b_0, b'_0, b''_0]) + [b_0, b'_0, i''] + [b_0, i', b''_0] + [i, b'_0, b''_0]) \\ &= p(p_0([b_0, b'_0, b''_0]) + \phi^I(p_1([b_0, b'_0, b''_0]) + [b_0, b'_0, i''] + [b_0, i', b''_0] + [i, b'_0, b''_0]) \\ &= [pb_0, pb'_0, pb''_0] + \omega(pb_0, pb'_0, pb''_0) + (-1)^{(b_0+b'_0)b''_0} L^*(pb_0, pb'_0) \phi^I(i'') \\ &\quad + (-1)^{b_0 b'_0} P^*(pb_0, pb'_0) \phi^I(i') + R^*(pb'_0, pb''_0) \phi^I(i) \\ &= [pb_0 + \phi^I(i), pb'_0 + \phi^I(i'), pb''_0 + \phi^I(i'')] \\ &= [m(b_0 + i), m(b'_0 + i'), m(b''_0 + i'')], \end{aligned}$$

where we use the definition of  $\omega$ , the intertwining properties of  $\phi^I$ , the fact that  $p$  is a homomorphism, the definition of the product in  $T_\omega^* B$ , lemma 4.1 and (4.1). In addition, we have

$$\begin{aligned} (m^* q_B)(b_0 + i, b'_0 + i') &= q_B(pb_0 + \phi^I(i), pb'_0 + \phi^I(i')) \\ &= \phi^I(i)(pb'_0) + \phi^I(i')(pb_0) \\ &= \phi(i, b'_0) + \phi(i', b) \\ &= \phi(b_0 + i, b'_0 + i'), \end{aligned}$$

where the fact that  $B_0$  could be chosen to be isotropic entered in the last equation. Hence,  $m^* q_B = \phi$  which implies that  $q_B$  is an invariant symmetric bilinear form on  $T_\omega^* B$  or that

$\omega$  is cyclic. Therefore,  $(T, \phi)$  and  $(T_\omega^*B, q_B)$  are isomorphic as metrised algebras and the theorem is proved.

The proof of this theorem shows that the trilinear map  $\omega$  depends on the choice of the isotropic subspace  $B_0$  of  $T$  complementary to the ideal  $I$ . Therefore, there may be different  $T^*$ -extensions describing the “same” metrised LSTS.

**Definition 4.1** *Let  $B_i$ ,  $i = 1, 2$ , be two LSTS's over a field  $\mathbb{K}$  and  $\omega_i : B_i \times B_i \times B_i \rightarrow B_i^*$ ,  $i = 1, 2$  be two different 3-supercocycles. The  $T^*$ -extension  $T_{\omega_i}^*B_i$  of  $B_i$  are said to be equivalent if  $B_1 = B_2 = B$  and there exists an isomorphism of LSTS  $\Phi : T_{\omega_1}^*B_1 \rightarrow T_{\omega_2}^*B_2$  which is the identity on the ideal  $B^*$  and which induces the identity on the factor LSTS  $T_{\omega_1}^*B_1/B^* = B = T_{\omega_2}^*B_2/B^*$ . The two  $T^*$ -extensions  $T_{\omega_i}^*B_i$  are said to be isometrically equivalent if they are equivalent and  $\Phi$  is an isometry.*

**Theorem 4.2** *Let  $B$  be an LSTS over a field of characteristic not equal to 2, and furthermore, let  $\omega_i$ ,  $i = 1, 2$  be two 3-supercocycles:  $B \times B \times B \rightarrow B^*$ .*

(i)  *$T_{\omega_i}^*B_i$  are equivalent if and only if there is a linear map  $z : B \rightarrow B^*$  such that for all  $a, b, c \in B$*

$$\begin{aligned} & \omega_1(a, b, c) - \omega_2(a, b, c) \\ &= (-1)^{(a+b)c}L^*(a, b)z(c) + (-1)^{ab}P^*(a, c)z(b) + R^*(b, c)z(a) - z([abc]). \end{aligned} \quad (4.2)$$

*If this is the case, then the supersymmetric part  $z_s$  of  $z$  which is defined by*

$$z_s(b)(d) := \frac{1}{2}(z(b)(d) + (-1)^{bd}z(d)(b)), \quad b, d \in B$$

*induces a symmetric invariant bilinear form on  $B$ , i.e.,*

$$z_s(a)([dcb]) = (-1)^{ab+bc}z_s(d)([abc]), \quad a, b, c, d \in B.$$

(ii)  *$T_{\omega_i}^*B_i$  are isometrically equivalent if and only if there is a linear map  $z : B \rightarrow B^*$  such that (4.2) holds for all  $a, b, c \in B$  and, in addition, the supersymmetric part  $z_s$  of  $z$  vanishes.*

*Proof.* (i) The equivalence between  $T_{\omega_1}^*B_1$  and  $T_{\omega_2}^*B_2$  holds if and only if there is a homomorphism of LSTS

$$\Phi : T_{\omega_1}^*B_1 \rightarrow T_{\omega_2}^*B_2$$

satisfying

$$\Phi(b + g) = b + z(b) + g, \quad b \in B, \quad g \in B^*,$$

where  $z$  is the component of  $\Phi$  that maps  $B$  to  $B^*$ . Indeed, by the definition,  $\Phi$  must be the identity on  $B^*$  and we must have

$$b = p(b) = p(\Phi(b)) = z_1(b),$$

where  $z_1(b)$  is the component of  $\Phi$  that maps  $B$  to  $B$ . Clearly,  $\Phi$  is a linear isomorphism for arbitrary  $z$ . Then for all  $a, b, c \in B$  and  $f, g, h \in B^*$ , we have

$$\begin{aligned} & \Phi([a + f, b + g, c + h]) \\ &= \Phi([abc]) + \omega_1(a, b, c) + (-1)^{(a+b)c}L^*(a, b)h + (-1)^{ab}P^*(a, c)g + R^*(b, c)f \\ &= [abc] + z([abc]) + \omega_1(a, b, c) + (-1)^{(a+b)c}L^*(a, b)h + (-1)^{ab}P^*(a, c)g + R^*(b, c)f, \end{aligned}$$

where the multiplication is formed in  $T_{\omega_1}^* B_1$ . On the other hand,

$$\begin{aligned} & [\Phi(a+f)\Phi(b+g)\Phi(c+h)] \\ &= [a+z(a)+f, b+z(b)+g, c+z(c)+h] \\ &= [abc] + \omega_2(a, b, c) + (-1)^{(a+b)c} L^*(a, b)h + (-1)^{(a+b)c} L^*(a, b)z(c) \\ &\quad + (-1)^{ab} P^*(a, c)g + (-1)^{ab} P^*(a, c)z(b) + R^*(b, c)f + R^*(b, c)z(a), \end{aligned}$$

where the multiplication is formed in  $T_{\omega_2}^* B_2$ . Hence  $\Phi$  is a homomorphism of LSTS if and only if (4.2) holds. Now split  $z$  into its anti-supersymmetric part  $z_a$  defined by

$$z_a(b)(d) := \frac{1}{2}(z(b)(d) - (-1)^{bd}z(d)(b)), \quad b, d \in B,$$

and its supersymmetric part  $z_s$  defined above. Then  $z = z_s + z_a$ . We see that the right hand side of (4.2) evaluated on  $d \in B$  has the following form:

$$\begin{aligned} & (-1)^{ac+bc+ab} z_a(c)([bad]) + (-1)^{a(b+c+d)} z_a(b)([cda]) + (-1)^{bc+bd+cd} z_a(a)([dcb]) \\ &+ (-1)^{d(b+c+a)} z_a(d)([abc]) + (-1)^{ac+bc+ab} z_s(c)([bad]) + (-1)^{a(b+c+d)} z_s(b)([cda]) \\ &+ (-1)^{bc+bd+cd} z_s(a)([dcb]) - (-1)^{d(b+c+a)} z_s(d)([abc]). \end{aligned}$$

Writing the above summation as  $s(abcd)$  and considering

$$s(abcd) - (-1)^{a(b+c+d)+b(c+d)+cd} s(dcba),$$

by Lemma 3.4(4), we get

$$z_s(a)([dcb]) = (-1)^{ab+bc} z_s(d)([abc]),$$

which proves the invariance of the supersymmetric bilinear form induced by  $z_s$ .

(ii) Let the isomorphism  $\Phi$  be defined as in (i). Then, we have for all  $b, d \in B$  and  $f, g \in B^*$

$$\begin{aligned} q_B(\Phi(b+f), \Phi(d+g)) &= q_B(b+z(b)+f, d+z(d)+g) \\ &= z(b)(d) + z(d)(b) + f(d) + g(b) \\ &= z(b)(d) + z(d)(b) + q_B(b+f, d+g), \end{aligned}$$

from which it is clear that  $\phi$  is an isometry if and only if  $z_s = 0$ .

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