# MODIFIED MORLEY ELEMENT METHOD FOR A FOURTH ORDER ELLIPTIC SINGULAR PERTURBATION PROBLEM *1) 

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#### Abstract

This paper proposes a modified Morley element method for a fourth order elliptic singular perturbation problem. The method also uses Morley element or rectangle Morley element, but linear or bilinear approximation of finite element functions is used in the lower part of the bilinear form. It is shown that the modified method converges uniformly in the perturbation parameter.


Mathematics subject classification: 65N30.
Key words: Morley element, Singular perturbation problem.

## 1. Introduction

Let $\Omega$ be a bounded polygonal domain of $R^{2}$. Denote the boundary of $\Omega$ by $\partial \Omega$. For $f \in L^{2}(\Omega)$, we consider the following boundary value problem of fourth order elliptic singular perturbation equation:

$$
\left\{\begin{array}{l}
\varepsilon^{2} \Delta^{2} u-\Delta u=f, \quad \text { in } \Omega  \tag{1.1}\\
\left.u\right|_{\partial \Omega}=\left.\frac{\partial u}{\partial \nu}\right|_{\partial \Omega}=0
\end{array}\right.
$$

where $\nu=\left(\nu_{1}, \nu_{2}\right)^{\top}$ is the unit outer normal to $\partial \Omega, \Delta$ is the standard Laplacian operator and $\varepsilon$ is a real small parameter with $0<\varepsilon \leq 1$. When $\varepsilon \rightarrow 0$ the differential equation formally degenerates to Poisson equation.

To overcome the $C^{1}$ difficult, it is prefer to using nonconforming finite element to solve problem (1.1). Since the differential equation degenerates to Poisson equation as $\varepsilon \rightarrow 0, C^{0}$ nonconforming elements seem better to be used. An $C^{0}$ nonconforming finite element was proposed in [4], and its uniform convergence in $\varepsilon$ was shown.

It is known that Morley element is not $C^{0}$ element and it is divergent for Poisson equation (see [6]). When Morley element is applied to solve problem (1.1), it fails when $\varepsilon \rightarrow 0$ (see [4]). On the other hand, we have noticed the remark in the end of paper [4]: the best result uniformly in $\varepsilon$ seems to be order of $O\left(h^{1 / 2}\right)$ for any finite element method to problem (1.1). Here $h$ is the mesh size. Since Morley element has the least number of element degrees of freedom, we prefer to use a method which still uses the degrees of freedom of Morley element to solve problem (1.1).

[^0]In this paper, we will propose a modified Morley element method for problem (1.1). The method also uses Morley element, but the linear approximation of finite element functions is used in the part of the bilinear form corresponding to the second order differential term. The modified method degenerates to the conforming linear element method for Poisson equation when $\varepsilon=0$, and this is consistent with the degenerate case of problem (1.1). We will show that the modified method converges uniformly in perturbation parameter $\varepsilon$.

The modified rectangle Morley element method is also considered in this paper.
The paper is organized as follows. The rest of this section lists some preliminaries. Section 2 gives the detail descriptions of the modified Morley element method. Section 3 shows the uniform convergence of the method. The last section gives some numerical results.

For nonnegative integer $s, H^{s}(\Omega),\|\cdot\|_{s, \Omega}$ and $|\cdot|_{s, \Omega}$ denote the usual Sobolev space, norm and semi-norm respectively. Let $H_{0}^{s}(\Omega)$ be the closure of $C_{0}^{\infty}(\Omega)$ in $H^{s}(\Omega)$ with respect to the norm $\|\cdot\|_{s, \Omega}$ and $(\cdot, \cdot)$ denote the inner product of $L^{2}(\Omega)$. Define

$$
\begin{gather*}
a(v, w)=\int_{\Omega} \sum_{i, j=1}^{2} \frac{\partial^{2} v}{\partial x_{i} \partial x_{j}} \frac{\partial^{2} w}{\partial x_{i} \partial x_{j}} \mathrm{~d} x, \quad \forall v, w \in H^{2}(\Omega)  \tag{1.2}\\
b(v, w)=\int_{\Omega} \sum_{i=1}^{2} \frac{\partial v}{\partial x_{i}} \frac{\partial w}{\partial x_{i}} \mathrm{~d} x, \quad \forall v, w \in H^{1}(\Omega) \tag{1.3}
\end{gather*}
$$

The weak form of problem (1.1) is: find $u \in H_{0}^{2}(\Omega)$ such that

$$
\begin{equation*}
\varepsilon^{2} a(u, v)+b(u, v)=(f, v), \quad \forall v \in H_{0}^{2}(\Omega) \tag{1.4}
\end{equation*}
$$

Let $u^{0}$ be the solution of following boundary value problem:

$$
\left\{\begin{array}{l}
-\Delta u^{0}=f, \quad \text { in } \Omega  \tag{1.5}\\
\left.u^{0}\right|_{\partial \Omega}=0
\end{array}\right.
$$

The following lemma is shown in paper [4].
Lemma 1.1. If $\Omega$ is convex, then there exists a constant $C$ independent of $\varepsilon$ such that

$$
\begin{gather*}
|u|_{2, \Omega}+\varepsilon|u|_{3, \Omega} \leq C \varepsilon^{-\frac{1}{2}}\|f\|_{0, \Omega}  \tag{1.6}\\
\left|u-u^{0}\right|_{1, \Omega} \leq C \varepsilon^{\frac{1}{2}}\|f\|_{0, \Omega} \tag{1.7}
\end{gather*}
$$

for all $f \in L^{2}(\Omega)$.

## 2. Modified Morley Element Method

For a subset $B \subset R^{2}$ and $r$ a nonnegative integer, let $P_{r}(B)$ be the space of all polynomials with degree not greater than $r$.

## Morley Element

Given a triangle $T$, its three vertices is denoted by $a_{j}, 1 \leq j \leq 3$. The edge of $T$ opposite $a_{j}$ is denoted by $F_{j}, 1 \leq j \leq 3$. Denote the measures of $T$ and $F_{i}$ by $|T|$ and $\left|F_{i}\right|$ respectively. Morley element can be described by $\left(T, P_{T}, \Phi_{T}\right)$ with

1) $T$ is a triangle.
2) $P_{T}=P_{2}(T)$.
3) $\Phi_{T}$ is the vector of degrees of freedom whose components are:

$$
v\left(a_{j}\right), \frac{1}{\left|F_{j}\right|} \int_{F_{j}} \frac{\partial v}{\partial \nu} \mathrm{~d} s, \quad 1 \leq j \leq 3
$$

for $v \in C^{1}(T)$.

## Rectangle Morley Element

Given a rectangle $T$, its four vertices and edges are denoted by $a_{j}$ and $F_{j}, 1 \leq j \leq 4$, respectively. Rectangle Morley element can be described by $\left(T, P_{T}, \Phi_{T}\right)$ with

1) $T$ is a rectangle with its edges parallel to some coordinate axes respectively.
2) $P_{T}=P_{2}(T)+\operatorname{span}\left\{x_{1}^{3}, x_{2}^{3}\right\}$.
3) $\Phi_{T}$ is the vector of degrees of freedom whose components are:

$$
v\left(a_{j}\right), \frac{1}{\left|F_{j}\right|} \int_{F_{j}} \frac{\partial v}{\partial \nu} \mathrm{~d} s, \quad 1 \leq j \leq 4
$$

for $v \in C^{1}(T)$.
The degrees of freedom of these two elements are shown in Fig. 1.


Morley element


Rectangle Morley element

Fig. 1
The Morley element and its convergence for biharmonic equations can be found in [1-3,5], while the rectangle Morley element in [7].

For mesh size $h$, take $\mathcal{T}_{h}$ a triangulation of $\Omega$. For Morley element $\mathcal{T}_{h}$ consists of triangles, otherwise $\mathcal{T}_{h}$ consists of rectangles with their edges parallel to some coordinate axes respectively. For each $T \in \mathcal{T}_{h}$, let $h_{T}$ be the diameter of the smallest disk containing $T$ and $\rho_{T}$ be the diameter of the largest disk contained in $T$. Let $\left\{\mathcal{I}_{h}\right\}$ be a family of triangulations with $h \rightarrow 0$. Throughout the paper, we assume that $\left\{\mathcal{T}_{h}\right\}$ is quasi-uniform, namely it satisfied that $h_{T} \leq$ $h \leq \eta \rho_{T}, \forall T \in \mathcal{T}_{h}$ for a positive constant $\eta$ independent of $h$.

For each $\mathcal{T}_{h}$, let $V_{h}$ and $V_{h 0}$ be the corresponding finite element spaces associated with Morley element or with rectangle Morley element for the discretization of $H^{2}(\Omega)$ and $H_{0}^{2}(\Omega)$ respectively. This defines two families of finite element spaces $\left\{V_{h}\right\}$ and $\left\{V_{h 0}\right\}$. It is known that $V_{h} \not \subset H^{2}(\Omega)$ and $V_{h 0} \not \subset H_{0}^{2}(\Omega)$. Let $\Pi_{h}$ be the interpolation operator corresponding to $\mathcal{T}_{h}$ and Morley element or the rectangular Morley element.

We define

$$
\begin{gather*}
a_{h}(v, w)=\sum_{T \in \mathcal{I}_{h}} \int_{T} \sum_{i, j=1}^{2} \frac{\partial^{2} v}{\partial x_{i} \partial x_{j}} \frac{\partial^{2} w}{\partial x_{i} \partial x_{j}} \mathrm{~d} x, v, w \in H^{2}(\Omega)+V_{h}  \tag{2.1}\\
b_{h}(v, w)=\sum_{T \in \mathcal{T}_{h}} \int_{T} \sum_{i=1}^{2} \frac{\partial v}{\partial x_{i}} \frac{\partial w}{\partial x_{i}} \mathrm{~d} x, v, w \in H^{1}(\Omega)+V_{h} \tag{2.2}
\end{gather*}
$$

The standard finite element method for problem (1.4) corresponding to Morley element or to rectangle Morley element is: find $u_{h} \in V_{h 0}$ such that

$$
\begin{equation*}
\varepsilon^{2} a_{h}\left(u_{h}, v_{h}\right)+b_{h}\left(u_{h}, v_{h}\right)=\left(f, v_{h}\right), \forall v_{h} \in V_{h 0} . \tag{2.3}
\end{equation*}
$$

For Morley element, let $\Pi_{h}^{1}$ be the interpolation operator corresponding to linear conforming element for second order partial differential equation and $\mathcal{T}_{h}$. For the rectangle Morley element
let $\Pi_{h}^{1}$ be the bilinear interpolation operator. We consider the following modified Morley element method: to find $u_{h} \in V_{h 0}$ such that

$$
\begin{equation*}
\varepsilon^{2} a_{h}\left(u_{h}, v_{h}\right)+b_{h}\left(\Pi_{h}^{1} u_{h}, \Pi_{h}^{1} v_{h}\right)=\left(f, \Pi_{h}^{1} v_{h}\right), \quad \forall v_{h} \in V_{h 0} \tag{2.4}
\end{equation*}
$$

Problem (2.4) has unique solution when $\varepsilon>0$. When $\varepsilon=0$, the problem degenerates to

$$
\begin{equation*}
b_{h}\left(\Pi_{h}^{1} u_{h}, \Pi_{h}^{1} v_{h}\right)=\left(f, \Pi_{h}^{1} v_{h}\right), \quad \forall v_{h} \in V_{h 0} \tag{2.5}
\end{equation*}
$$

Although the solution of problem (2.5) is not unique yet, $\Pi_{h}^{1} u_{h}$ is uniquely determined. Actually, $\Pi_{h}^{1} u_{h}$ is the exact finite element solution of linear or bilinear conforming elemet for problem (1.5). Hence the modified Morley element method seems to give a more natural way to solve problem (1.1).

We introduce the following mesh dependent norm $\|\cdot\|_{m, h}$ and semi-norm $|\cdot|_{m, h}$ :

$$
\left\{\begin{array}{l}
\|v\|_{m, h}=\left(\sum_{T \in \mathcal{T}_{h}}\|v\|_{m, T}^{2}\right)^{1 / 2} \\
|v|_{m, h}=\left(\sum_{T \in \mathcal{T}_{h}}|v|_{m, T}^{2}\right)^{1 / 2}
\end{array} \quad \forall v \in V_{h}+H^{m}(\Omega)\right.
$$

## 3. Convergence Analysis

In this section, we discuss the convergence properties of the modified Morley element methods in previous section.

Let $u$ and $u_{h}$ be the solutions of problem (1.4) and (2.4) respectively.
Lemma 3.1. There exists a constant $C$ independent of $h$ and $\varepsilon$ such that $\forall v_{h} \in V_{h 0}$

$$
\begin{gather*}
\left|b_{h}\left(\Pi_{h}^{1} u, \Pi_{h}^{1} v_{h}\right)+\left(\Delta u, \Pi_{h}^{1} v_{h}\right)\right| \leq C h|u|_{2, \Omega}\left|\Pi_{h}^{1} v_{h}\right|_{1, h}  \tag{3.1}\\
\left|a_{h}\left(u, v_{h}\right)-\left(\Delta^{2} u, \Pi_{h}^{1} v_{h}\right)\right| \leq C h|u|_{3, \Omega}\left|v_{h}\right|_{2, h} \tag{3.2}
\end{gather*}
$$

when $u \in H^{3}(\Omega)$.
Proof. Let $v_{h} \in V_{h 0}$. Then $\Pi_{h}^{1} v_{h} \in H_{0}^{1}(\Omega)$ and

$$
\left|b_{h}\left(\Pi_{h}^{1} u, \Pi_{h}^{1} v_{h}\right)+\left(\Delta u, \Pi_{h}^{1} v_{h}\right)\right|=\left|b_{h}\left(u-\Pi_{h}^{1} u, \Pi_{h}^{1} v_{h}\right)\right| .
$$

By the interpolation theory and Schwarz inequality we obtain (3.1).
Now take $\phi \in H^{1}(\Omega)$. Given $T \in \mathcal{T}_{h}$ and an edge $F$ of $T$, let $P_{F}^{0}$ be the orthogonal projection operator from $L^{2}(F)$ to $P_{0}(F)$.

Let $i, j \in\{1,2\}$. It is known that the integral average of $\frac{\partial}{\partial x_{j}} v_{h}$ on $F$ is continuous through $F$ and vanishes when $F \subset \partial \Omega$. Then Green formula gives

$$
\begin{aligned}
\sum_{T \in \mathcal{T}_{h}} \int_{T} & \left(\phi \frac{\partial^{2} v_{h}}{\partial x_{i} \partial x_{j}}+\frac{\partial \phi}{\partial x_{i}} \frac{\partial v_{h}}{\partial x_{j}}\right) \mathrm{d} x \\
& =\sum_{T \in \mathcal{T}_{h}} \int_{\partial T} \phi \frac{\partial v_{h}}{\partial x_{j}} \nu_{i} \mathrm{~d} s=\sum_{T \in \mathcal{T}_{h}} \sum_{F \subset \partial T} \int_{F} \phi \frac{\partial v_{h}}{\partial x_{j}} \nu_{i} \mathrm{~d} s \\
& =\sum_{T \in \mathcal{T}_{h}} \sum_{F \subset \partial T} \int_{F} \phi\left(\frac{\partial v_{h}}{\partial x_{j}}-P_{F}^{0} \frac{\partial v_{h}}{\partial x_{j}}\right) \nu_{i} \mathrm{~d} s \\
& =\sum_{T \in \mathcal{T}_{h}} \sum_{F \subset \partial T} \int_{F}\left(\phi-P_{F}^{0} \phi\right)\left(\frac{\partial v_{h}}{\partial x_{j}}-P_{F}^{0} \frac{\partial v_{h}}{\partial x_{j}}\right) \nu_{i} \mathrm{~d} s
\end{aligned}
$$

From Schwarz inequality and the interpolation theory we have

$$
\begin{aligned}
&\left|\sum_{T \in \mathcal{T}_{h}} \sum_{F \subset \partial T} \int_{F}\left(\phi-P_{F}^{0} \phi\right)\left(\frac{\partial v_{h}}{\partial x_{j}}-P_{F}^{0} \frac{\partial v_{h}}{\partial x_{j}}\right) \nu_{i} \mathrm{~d} s\right| \\
& \leq \sum_{T \in \mathcal{T}_{h}} \sum_{F \subset \partial T}\left\|\phi-P_{F}^{0} \phi\right\|_{0, F}\left\|\frac{\partial v_{h}}{\partial x_{j}}-P_{F}^{0} \frac{\partial v_{h}}{\partial x_{j}}\right\|_{0, F} \\
& \leq C \sum_{T \in \mathcal{T}_{h}} h|\phi|_{1, T}\left|v_{h}\right|_{2, T} \leq C h|\phi|_{1, \Omega}\left|v_{h}\right|_{2, h}
\end{aligned}
$$

Consequently, we obtain that $\forall \phi \in H^{1}(\Omega), \forall v_{h} \in V_{h 0}, i, j \in\{1,2\}$,

$$
\begin{equation*}
\left|\sum_{T \in \mathcal{T}_{h}} \int_{T}\left(\phi \frac{\partial^{2} v_{h}}{\partial x_{i} \partial x_{j}}+\frac{\partial \phi}{\partial x_{i}} \frac{\partial v_{h}}{\partial x_{j}}\right) \mathrm{d} x\right| \leq C h|\phi|_{1, \Omega}\left|v_{h}\right|_{2, h} \tag{3.3}
\end{equation*}
$$

We obtain the conclusion of the lemma from (3.3), the interpolation theory and the following equality,

$$
\begin{align*}
a_{h}\left(u, v_{h}\right) & -\left(\Delta^{2} u, \Pi_{h}^{1} v_{h}\right) \\
= & \sum_{i=1}^{2} \sum_{T \in \mathcal{T}_{h}} \int_{T} \frac{\partial \Delta u}{\partial x_{i}} \frac{\partial\left(\Pi_{h}^{1} v_{h}-v_{h}\right)}{\partial x_{i}} \mathrm{~d} x \\
& +\sum_{i=1}^{2} \sum_{T \in \mathcal{T}_{h}} \int_{T}\left(\Delta u \frac{\partial^{2} v_{h}}{\partial x_{i}^{2}}+\frac{\partial \Delta u}{\partial x_{i}} \frac{\partial v_{h}}{\partial x_{i}}\right) \mathrm{d} x  \tag{3.4}\\
& +\sum_{1 \leq i \neq j \leq 2} \sum_{T \in \mathcal{T}_{h}} \int_{T}\left(\frac{\partial^{2} u}{\partial x_{i} \partial x_{j}} \frac{\partial^{2} v_{h}}{\partial x_{i} \partial x_{j}}+\frac{\partial^{3} u}{\partial x_{i}^{2} \partial x_{j}} \frac{\partial v_{h}}{\partial x_{j}}\right) \mathrm{d} x \\
& -\sum_{1 \leq i \neq j \leq 2} \sum_{T \in \mathcal{T}_{h}} \int_{T}\left(\frac{\partial^{2} u}{\partial x_{i}^{2}} \frac{\partial^{2} v_{h}}{\partial x_{j}^{2}}+\frac{\partial^{3} u}{\partial x_{i}^{2} \partial x_{j}} \frac{\partial v_{h}}{\partial x_{j}}\right) \mathrm{d} x
\end{align*}
$$

From lemma 3.1, we have
Theorem 3.1. There exists a constant $C$ independent of $h$ and $\varepsilon$ such that

$$
\begin{equation*}
\varepsilon\left\|u-u_{h}\right\|_{2, h}+\left\|u-\Pi_{h}^{1} u_{h}\right\|_{1, \Omega} \leq C h\left(\varepsilon|u|_{3, \Omega}+|u|_{2, \Omega}\right) \tag{3.5}
\end{equation*}
$$

when $u \in H^{3}(\Omega)$.
Proof. Let $w_{h}=\Pi_{h} u$, then

$$
\begin{align*}
\varepsilon\left\|u-u_{h}\right\|_{2, h}+\left\|u-\Pi_{h}^{1} u_{h}\right\|_{1, \Omega} \leq & \varepsilon\left\|u-w_{h}\right\|_{2, h}+\left\|u-\Pi_{h}^{1} w_{h}\right\|_{1, \Omega}  \tag{3.6}\\
& +\varepsilon\left\|u_{h}-w_{h}\right\|_{2, h}+\left\|\Pi_{h}^{1}\left(u_{h}-w_{h}\right)\right\|_{1, \Omega}
\end{align*}
$$

Set $v_{h}=u_{h}-w_{h}$. From (2.4) and (1.1), we have

$$
\begin{aligned}
\varepsilon^{2} a_{h}\left(v_{h}, v_{h}\right)+ & b_{h}\left(\Pi_{h}^{1} v_{h}, \Pi_{h}^{1} v_{h}\right) \\
= & \varepsilon^{2} a_{h}\left(u-w_{h}, v_{h}\right)+b_{h}\left(\Pi_{h}^{1}\left(u-w_{h}\right), \Pi_{h}^{1} v_{h}\right) \\
& +\varepsilon^{2}\left(\left(\Delta^{2} u, \Pi_{h}^{1} v_{h}\right)-a_{h}\left(u, v_{h}\right)\right) \\
& -\left(\left(\Delta u, \Pi_{h}^{1} v_{h}\right)+b_{h}\left(\Pi_{h}^{1} u, \Pi_{h}^{1} v_{h}\right)\right)
\end{aligned}
$$

From the interpolation theory, (3.1) and (3.2),

$$
\varepsilon^{2} a_{h}\left(v_{h}, v_{h}\right)+b_{h}\left(\Pi_{h}^{1} v_{h}, \Pi_{h}^{1} v_{h}\right) \leq C h\left(\varepsilon|u|_{3, \Omega}+|u|_{2, \Omega}\right)\left(\varepsilon\left|v_{h}\right|_{2, h}+\left|\Pi_{h}^{1} v_{h}\right|_{1, \Omega}\right)
$$

Since

$$
\varepsilon^{2}\left\|v_{h}\right\|_{2, h}^{2}+\left\|\Pi_{h}^{1} v_{h}\right\|_{1, \Omega}^{2} \leq C\left(\varepsilon^{2} a_{h}\left(v_{h}, v_{h}\right)+b_{h}\left(\Pi_{h}^{1} v_{h}, \Pi_{h}^{1} v_{h}\right)\right)
$$

we obtain that

$$
\begin{equation*}
\varepsilon\left\|u_{h}-w_{h}\right\|_{2, h}+\left\|\Pi_{h}^{1}\left(u_{h}-w_{h}\right)\right\|_{1, \Omega} \leq C h\left(\varepsilon|u|_{3, \Omega}+|u|_{2, \Omega}\right) \tag{3.7}
\end{equation*}
$$

The theorem follows from the interpolation theory, (3.6) and (3.7).
Theorem 3.2. If $\Omega$ is convex, then there exists a constant $C$ independent of $h$ and $\varepsilon$ such that

$$
\begin{equation*}
\varepsilon\left\|u-u_{h}\right\|_{2, h}+\left\|u-\Pi_{h}^{1} u_{h}\right\|_{1, \Omega} \leq C h^{1 / 2}\|f\|_{0, \Omega} \tag{3.8}
\end{equation*}
$$

Proof. From the interpolation theory,

$$
\left\|u-\Pi_{h} u\right\|_{2, h}^{2} \leq C|u|_{2, \Omega}\left\|u-\Pi_{h} u\right\|_{2, h} \leq C h|u|_{2, \Omega}|u|_{3, \Omega}
$$

By lemma 1.1, we have

$$
\begin{equation*}
\varepsilon\left\|u-\Pi_{h} u\right\|_{2, h} \leq C h^{1 / 2}\|f\|_{0, \Omega} \tag{3.9}
\end{equation*}
$$

Similar to (4.4) in [4], we can show that

$$
\begin{equation*}
\left\|v-\Pi_{h}^{1} v\right\|_{1, \Omega}^{2} \leq C h|v|_{1, \Omega}|v|_{2, \Omega}, \quad \forall v \in H_{0}^{2}(\Omega) \tag{3.10}
\end{equation*}
$$

Using (3.10), we obtain

$$
\left\|u-u^{0}-\Pi_{h}^{1}\left(u-u^{0}\right)\right\|_{1, \Omega}^{2} \leq C h\left|u-u^{0}\right|_{1, \Omega}\left|u-u^{0}\right|_{2, \Omega}
$$

and by the interpolation theory,

$$
\left\|u^{0}-\Pi_{h}^{1} u^{0}\right\|_{1, \Omega} \leq C h\left|u^{0}\right|_{2, \Omega}
$$

From lemma 1.1 and the following inequalities

$$
\begin{gathered}
\left\|u^{0}\right\|_{2, \Omega} \leq C\|f\|_{0, \Omega} \\
\left\|u-\Pi_{h}^{1} u\right\|_{1, \Omega} \leq\left\|u-u^{0}-\Pi_{h}^{1}\left(u-u^{0}\right)\right\|_{1, \Omega}+\left\|u^{0}-\Pi_{h}^{1} u^{0}\right\|_{1, \Omega}
\end{gathered}
$$

we have

$$
\begin{equation*}
\left\|u-\Pi_{h}^{1} u\right\|_{1, \Omega} \leq C h^{1 / 2}\|f\|_{0, \Omega} \tag{3.11}
\end{equation*}
$$

Set $v_{h}=u_{h}-\Pi_{h} u$. Then $\Pi_{h}^{1} v_{h} \in H_{0}^{1}(\Omega)$ and

$$
\left|b_{h}\left(\Pi_{h}^{1} u, \Pi_{h}^{1} v_{h}\right)+\left(\Delta u, \Pi_{h}^{1} v_{h}\right)\right|=\left|b_{h}\left(u-\Pi_{h}^{1} u, \Pi_{h}^{1} v_{h}\right)\right| .
$$

From (3.11) and Schwarz inequality,

$$
\begin{equation*}
\left|b_{h}\left(\Pi_{h}^{1} u, \Pi_{h}^{1} v_{h}\right)+\left(\Delta u, \Pi_{h}^{1} v_{h}\right)\right| \leq C h^{1 / 2}\|f\|_{0, \Omega}\left\|\Pi_{h}^{1} v_{h}\right\|_{1, \Omega} \tag{3.12}
\end{equation*}
$$

Now take $\phi \in H^{1}(\Omega)$ and $i, j \in\{1,2\}$. From the proof of lemma 3.1, we have

$$
\begin{aligned}
& \left|\sum_{T \in \mathcal{T}_{h}} \int_{T}\left(\phi \frac{\partial^{2} v_{h}}{\partial x_{i} \partial x_{j}}+\frac{\partial \phi}{\partial x_{i}} \frac{\partial v_{h}}{\partial x_{j}}\right) \mathrm{d} x\right| \\
& \quad \leq \sum_{T \in \mathcal{T}_{h}} \sum_{F \subset \partial T}\left\|\phi-P_{F}^{0} \phi\right\|_{0, F}\left\|\frac{\partial v_{h}}{\partial x_{j}}-P_{F}^{0} \frac{\partial v_{h}}{\partial x_{j}}\right\|_{0, F}
\end{aligned}
$$

Since

$$
\begin{equation*}
\left\|\phi-P_{F}^{0} \phi\right\|_{0, F} \leq 2\|\phi\|_{0, F} \leq 2\|\phi\|_{0, \partial T} \leq C\|\phi\|_{0, T}^{1 / 2}\|\phi\|_{1, T}^{1 / 2} \tag{3.13}
\end{equation*}
$$

we have, by the interpolation theory

$$
\begin{equation*}
\left|\sum_{T \in \mathcal{T}_{h}} \int_{T}\left(\phi \frac{\partial^{2} v_{h}}{\partial x_{i} \partial x_{j}}+\frac{\partial \phi}{\partial x_{i}} \frac{\partial v_{h}}{\partial x_{j}}\right) \mathrm{d} x\right| \leq C h^{1 / 2}\|\phi\|_{0, \Omega}^{1 / 2}\|\phi\|_{1, \Omega}^{1 / 2}\left|v_{h}\right|_{2, h} . \tag{3.14}
\end{equation*}
$$

If $\varepsilon \leq h$, then by Green formula

$$
\sum_{T \in \mathcal{T}_{h}} \int_{T} \frac{\partial \phi}{\partial x_{i}} \frac{\partial\left(\Pi_{h}^{1} v_{h}-v_{h}\right)}{\partial x_{i}} \mathrm{~d} x=\sum_{T \in \mathcal{T}_{h}} \int_{\partial T} \phi \frac{\partial\left(\Pi_{h}^{1} v_{h}-v_{h}\right)}{\partial x_{i}} \nu_{i} \mathrm{~d} s
$$

$$
-\sum_{T \in \mathcal{T}_{h}} \int_{T} \phi \frac{\partial^{2}\left(\Pi_{h}^{1} v_{h}-v_{h}\right)}{\partial x_{i}^{2}} \mathrm{~d} x
$$

From Schwarz inequality, the interpolation thoery and (3.13), we obtain

$$
\begin{aligned}
\left|\sum_{T \in \mathcal{T}_{h}} \int_{T} \frac{\partial \phi}{\partial x_{i}} \frac{\partial\left(\Pi_{h}^{1} v_{h}-v_{h}\right)}{\partial x_{i}} \mathrm{~d} x\right| \leq & \sum_{T \in \mathcal{T}_{h}}\|\phi\|_{0, \partial T}\left\|\frac{\partial\left(\Pi_{h}^{1} v_{h}-v_{h}\right)}{\partial x_{i}}\right\|_{0, \partial T} \\
& +\sum_{T \in \mathcal{T}_{h}}\|\phi\|_{0, T}\left|\Pi_{h}^{1} v_{h}-v_{h}\right|_{2, T} \\
\leq & C\left(h^{1 / 2}\|\phi\|_{0, \Omega}^{1 / 2}\|\phi\|_{1, \Omega}^{1 / 2}+\|\phi\|_{0, \Omega}\right)\left|v_{h}\right|_{2, h} .
\end{aligned}
$$

Hence when $\varepsilon \leq h$

$$
\begin{equation*}
\varepsilon^{2}\left|\sum_{T \in \mathcal{T}_{h}} \int_{T} \frac{\partial \phi}{\partial x_{i}} \frac{\partial\left(\Pi_{h}^{1} v_{h}-v_{h}\right)}{\partial x_{i}} \mathrm{~d} x\right| \leq C h^{1 / 2}\left(\varepsilon^{2}\|\phi\|_{0, \Omega}^{1 / 2}\|\phi\|_{1, \Omega}^{1 / 2}+\varepsilon^{3 / 2}\|\phi\|_{0, \Omega}\right)\left|v_{h}\right|_{2, h} \tag{3.15}
\end{equation*}
$$

When $\varepsilon>h$, by Schwarz inequality and the interpolation theory we have,

$$
\begin{equation*}
\varepsilon^{2}\left|\sum_{T \in \mathcal{I}_{h}} \int_{T} \frac{\partial \phi}{\partial x_{i}} \frac{\partial\left(\Pi_{h}^{1} v_{h}-v_{h}\right)}{\partial x_{i}} \mathrm{~d} x\right| \leq C h \varepsilon^{2}|\phi|_{1, \Omega}\left|v_{h}\right|_{2, h} \leq C h^{1 / 2} \varepsilon^{5 / 2}|\phi|_{1, \Omega}\left|v_{h}\right|_{2, h} . \tag{3.16}
\end{equation*}
$$

From lemma 1.1, (3.4), (3.14), (3.15) and (3.16) we obtain

$$
\begin{equation*}
\varepsilon^{2}\left|a_{h}\left(u, v_{h}\right)-\left(\Delta^{2} u, \Pi_{h}^{1} v_{h}\right)\right| \leq C \varepsilon h^{1 / 2}\|f\|_{0, \Omega}\left|v_{h}\right|_{2, h} \tag{3.17}
\end{equation*}
$$

Combining (3.9), (3.11), (3.12), (3.17) and the proof of theorem 3.1, we obtain the theorem.

## 4. Numerical Results

In this section, we will show some numerical results of the modified Morley element methods. We will use the same example used in [4] for comparison.

Let $\Omega=[0,1] \times[0,1]$ and $u(x)=\left(\sin \left(\pi x_{1}\right) \sin \left(\pi x_{2}\right)\right)^{2}$. For $\varepsilon \geq 0$, set $f=\varepsilon^{2} \Delta^{2} u-\Delta u$. Then $u$ is the solution of problem (1.1) when $\varepsilon>0$, and is the solution of problem (1.5) when $\varepsilon=0$. For the rectangle Morley element, $\Omega$ is divided into $h \times h$ squares, and for Morley element, each square is further divided into two triangles by the diagonal with a negative slash.

Define

$$
\left\|v_{h}\right\|_{\varepsilon, h}=\left(\varepsilon^{2} a_{h}\left(v_{h}, v_{h}\right)+b_{h}\left(\Pi_{h}^{1} v_{h}, \Pi_{h}^{1} v_{h}\right)\right)^{1 / 2}, \quad \forall v_{h} \in V_{h 0} .
$$

Different values of $\varepsilon$ and $h$ are chosen to demonstrate the behaviors of the following relative error of two modified Morley element methods,

$$
\begin{equation*}
E_{\varepsilon, h}=\frac{\left\|u_{h}^{I}-u_{h}\right\|_{\varepsilon, h}}{\left\|u_{h}^{I}\right\|_{\varepsilon, h}} \tag{4.1}
\end{equation*}
$$

where $u_{h}$ is the solution of problem (2.4) and $u_{h}^{I}$ denote the interpolant of $u$ by Morley element or rectangular Morley element.

Let $g=\Delta^{2} u$, then $u$ is the solution of the following boundary value problem of biharmonic equation,

$$
\left\{\begin{array}{l}
\Delta^{2} u=g,  \tag{4.2}\\
\left.u\right|_{\partial \Omega}=\left.\frac{\partial u}{\partial \nu}\right|_{\partial \Omega}=0
\end{array}\right.
$$

For comparison, we also consider the error of finite element solution to problem (4.2). Let $\tilde{u}_{h} \in V_{h 0}$ be the solution of the following problem,

$$
\begin{equation*}
a_{h}\left(\tilde{u}_{h}, v_{h}\right)=\left(g, \Pi_{h}^{1} v_{h}\right), \quad \forall v_{h} \in V_{h 0} . \tag{4.3}
\end{equation*}
$$

In this situation, the relative error $\tilde{E}_{h}$ is presented by

$$
\begin{equation*}
\tilde{E}_{h}^{2}=\frac{a_{h}\left(u_{h}^{I}-\tilde{u}_{h}, u_{h}^{I}-\tilde{u}_{h}\right)}{a_{h}\left(u_{h}^{I}, u_{h}^{I}\right)} \tag{4.4}
\end{equation*}
$$

For the modified Morley element method and the modified rectangular Morley element method, $E_{\varepsilon, h}$ and $\tilde{E}_{h}$, corresponding some $\varepsilon$ and $h$, are listed in Table 1 and Table 2 respectively.
Table 1. Modified Morley Element Method

| $\varepsilon \backslash h$ | $2^{-3}$ | $2^{-4}$ | $2^{-5}$ | $2^{-6}$ |
| :---: | :---: | :---: | :---: | :---: |
| 0 | 0.0576 | 0.0145 | 0.0036 | 0.0009 |
| $2^{-10}$ | 0.0577 | 0.0146 | 0.0037 | 0.0009 |
| $2^{-8}$ | 0.0586 | 0.0156 | 0.0046 | 0.0017 |
| $2^{-6}$ | 0.0713 | 0.0266 | 0.0119 | 0.0057 |
| $2^{-4}$ | 0.1653 | 0.0832 | 0.0418 | 0.0210 |
| $2^{-2}$ | 0.3404 | 0.1749 | 0.0885 | 0.0451 |
| $2^{0}$ | 0.3869 | 0.1979 | 0.1000 | 0.0512 |
| Biharmonic | 0.3908 | 0.1998 | 0.1010 | 0.0517 |

Table 2. Modified Rectangular Morley Element Method

| $\varepsilon \backslash h$ | $2^{-3}$ | $2^{-4}$ | $2^{-5}$ | $2^{-6}$ |
| :---: | :---: | :---: | :---: | :---: |
| 0 | 0.0205 | 0.0046 | 0.0011 | 0.0002 |
| $2^{-10}$ | 0.0205 | 0.0047 | 0.0011 | 0.0003 |
| $2^{-8}$ | 0.0211 | 0.0052 | 0.0016 | 0.0006 |
| $2^{-6}$ | 0.0285 | 0.0107 | 0.0049 | 0.0024 |
| $2^{-4}$ | 0.0757 | 0.0360 | 0.0179 | 0.0091 |
| $2^{-2}$ | 0.1568 | 0.0770 | 0.0392 | 0.0211 |
| $2^{0}$ | 0.1774 | 0.0875 | 0.0449 | 0.0246 |
| Biharmonic | 0.1791 | 0.0884 | 0.0453 | 0.0249 |

From Table 1 we see that the modified Morley element method, unlike Morley element method (see Table 1 in [4]), converges for all $\varepsilon \in[0,1]$. More precisely, the result shows that $E_{\varepsilon, h}$ tends to $E_{0, h}$ as $\varepsilon$ approaches 0 , while $E_{\varepsilon, h}$ is linear with respect to $h$ as well as $\tilde{E}_{h}$ is when $\varepsilon$ is large. That is, the modified Morley element method behaves in the way that the conforming linear element does for Poisson equation when $\varepsilon$ is small, while it likes Morley element for the biharmoni equation when $\varepsilon$ is large.

We can get the similar discussion about the modified rectangular Morley element method from Table 2.

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