

Characterizing Continuous dcpos by Liminf Convergence of Filters*

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Abstract: It is proved in this note that, under a mild assumption, a dcpo L is continuous if and only if the liminf convergence on L is topological.

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1 Introduction

The interaction between order theoretic and topological properties is an important topic in order theory (see [1]–[6]). A well-known result is that a dcpo L is continuous if and only if the S -convergence on L is topological. It is proved that in a continuous dcpo the liminf convergence of nets is topological and agrees with convergence in Lawson topology (see [1], Theorem III-3.17). The purpose of this note is to show that the converse is also true under a mild assumption. Precisely, for a strong meet continuous dcpo L , the liminf convergence of nets on L is topological if and only if L is continuous.

2 Convergence Spaces

This section recalls some basic notions of convergence spaces. For each set X , let $F(X)$ denote the set of filters on X . For each $x \in X$, $\hat{x} = \{A \subseteq X \mid x \in A\}$ denotes the principal filter generated by $\{x\}$.

A convergence structure on X is a subset $\mathcal{T} \subseteq F(X) \times X$ subject to the following conditions:

- (1) $(\hat{x}, x) \in \mathcal{T}$ for all $x \in X$;
- (2) $(\mathcal{F}, x) \in \mathcal{T}, \mathcal{F} \subseteq \mathcal{G} \implies (\mathcal{G}, x) \in \mathcal{T}$.

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The pair (X, \mathcal{T}) is called a convergence space. If $(\mathcal{F}, x) \in \mathcal{T}$, we also write $\mathcal{F} \xrightarrow{\mathcal{T}} x$ or simply $\mathcal{F} \rightarrow x$ if no confusion will arise. A function $f : X \rightarrow Y$ between two convergence spaces is continuous if $\mathcal{F} \rightarrow x$ implies that $f(\mathcal{F}) \rightarrow f(x)$, where $f(\mathcal{F})$ is the filter on Y generated by $\{f(A) \mid A \in \mathcal{F}\}$.

The category of convergence spaces and continuous functions is denoted by Conv . It is well-known that Conv is topological over the category of sets (see [7]), and hence it is complete and cocomplete. In particular, the product $(X_1 \times X_2, \mathcal{T}_1 \times \mathcal{T}_2)$ of two convergence spaces (X_1, \mathcal{T}_1) and (X_2, \mathcal{T}_2) is given as follows: a filter \mathcal{F} on $X_1 \times X_2$ converges to (x_1, x_2) with respect to $\mathcal{T}_1 \times \mathcal{T}_2$ if and only if there exist $(\mathcal{F}_1, x_1) \in \mathcal{T}_1$ and $(\mathcal{F}_2, x_2) \in \mathcal{T}_2$ such that $\{A \times B \mid A \in \mathcal{F}_1, B \in \mathcal{F}_2\} \subseteq \mathcal{F}$. Note that here we use the symbol $\mathcal{T}_1 \times \mathcal{T}_2$ to denote the product convergence structure, not the cartesian product of \mathcal{T}_1 and \mathcal{T}_2 (as sets), which will cause no confusion.

Given a topological space X , $\mathcal{T} = \{(\mathcal{F}, x) \mid \mathcal{F} \rightarrow x\}$ is a convergence structure on X . This correspondence is indeed a functorial embedding of the category Top of topological spaces in Conv .

Definition 2.1 *Let (X, \mathcal{T}) be a convergence space.*

- (1) (X, \mathcal{T}) is called a Kent convergence space if
(K) $\mathcal{F} \rightarrow x \implies \mathcal{F} \cap \hat{x} \rightarrow x$.
- (2) (X, \mathcal{T}) is called a limit space if
(Lim) $\mathcal{F} \rightarrow x, \mathcal{G} \rightarrow x \implies \mathcal{F} \cap \mathcal{G} \rightarrow x$.
- (3) (X, \mathcal{T}) is called a pretopological space if
(PrT) $\mathcal{F}_j \rightarrow x, \forall j \in J \implies \bigcap_{j \in J} \mathcal{F}_j \rightarrow x$.
- (4) (X, \mathcal{T}) is called topological if \mathcal{T} is generated by some topology on X .

It is clear that every topological convergence space is pretopological, every pretopological space is a limit space, and every limit space is a Kent convergence space. The full subcategories consisting of Kent convergence spaces, limit spaces, and pretopological spaces are denoted respectively by KConv , Lim , and PrTop . Then

$$\text{Top} \subset \text{PrTop} \subset \text{Lim} \subset \text{KConv} \subset \text{Conv}.$$

It is well known (e.g., [8]) that every category in the above diagram contains the preceding ones as reflective subcategories.

3 S -convergence

A dcpo is a partially ordered set L such that every directed set $D \subseteq L$ has a supremum. We write DCPO for the category of dcpos and functions that preserve directed suprema.

Definition 3.1 *Let \mathcal{F} be a filter on a dcpo L .*

- (1) $z \in L$ is an eventual lower bound of \mathcal{F} if $\uparrow z \in \mathcal{F}$.
- (2) \mathcal{F} S -converges to $x \in L$ (in symbols, $\mathcal{F} \rightarrow_S x$) if there exists a directed set D contained in the eventual lower bounds of \mathcal{F} with $x \leq \sup D$.